

# Dynamic Mesh Adaptation of massive unstructured grids for the simulation of flame fronts and gas/liquid interfaces

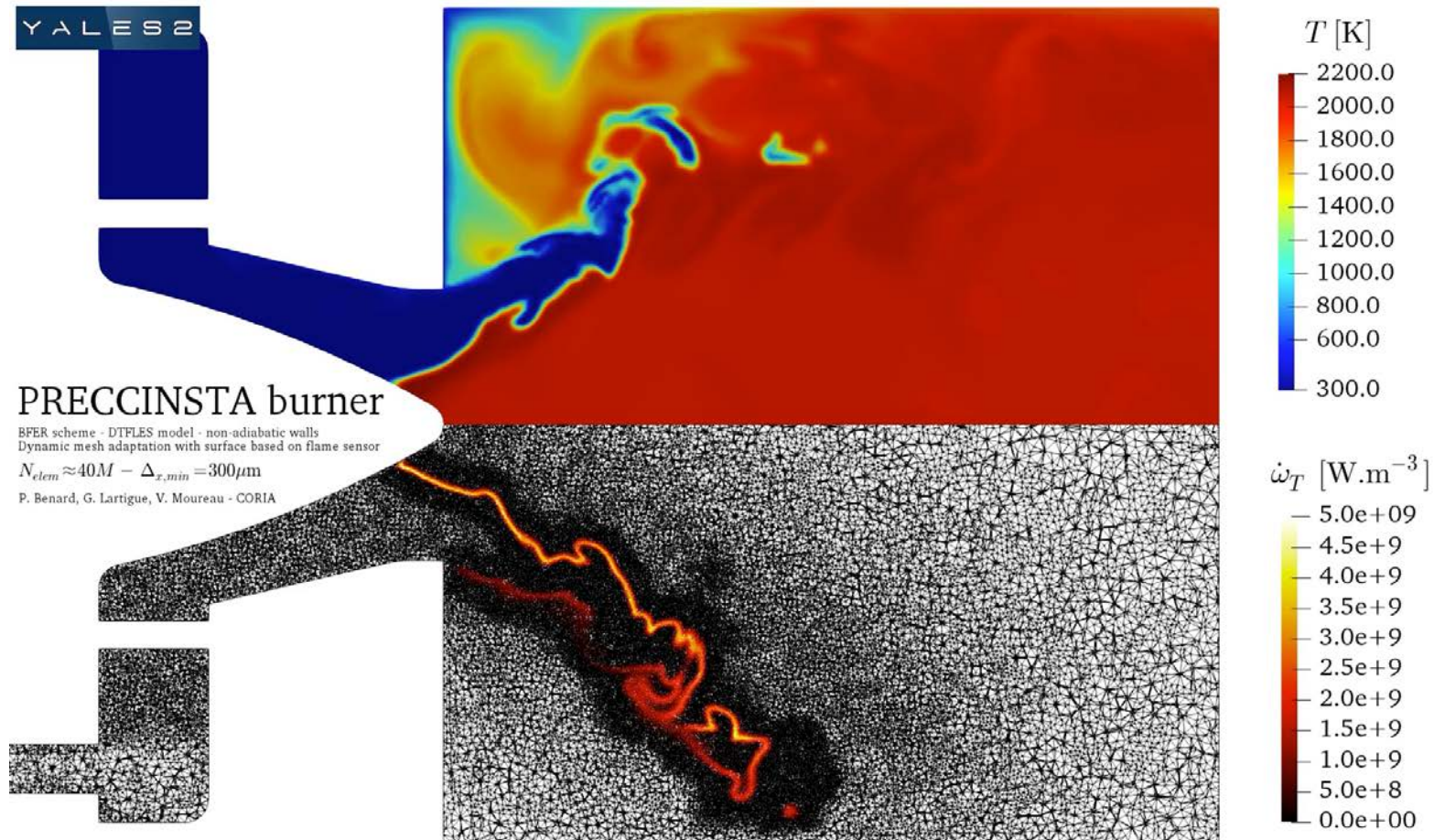
V. Moureau, P. Bénard, K. Bioche, J. Carmona, L. Voivenel, Y. Béchane  
CORIA, CNRS UMR6614, Normandie Univ, UNIROUEN, INSA Rouen, France

P. Begou, G. Balarac, G. Ghigliotti, – LEGI, Grenoble, France

A. Froehly, C. Dobrzynski – LMB/INRIA Bordeaux, France

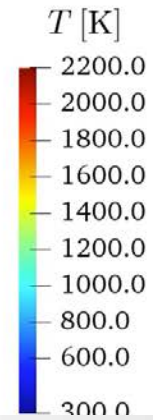
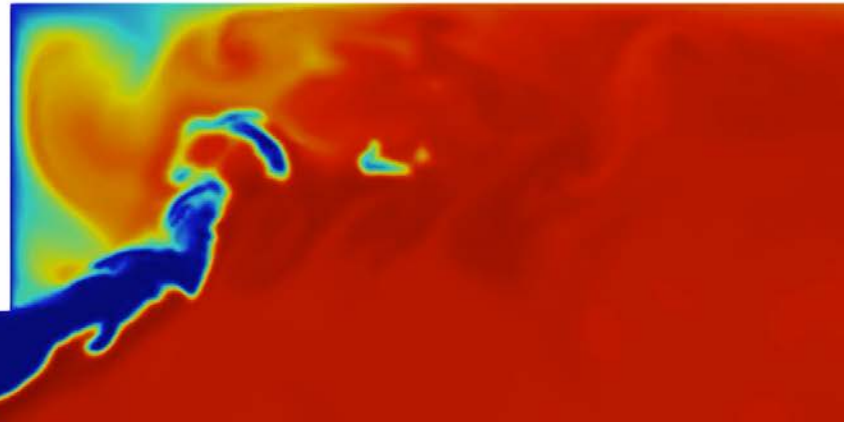
R. Mercier, M. Cailler, J. Leparoux, R. Letournel  
SAFRAN Tech, Magny-les-H., France

# Motivation



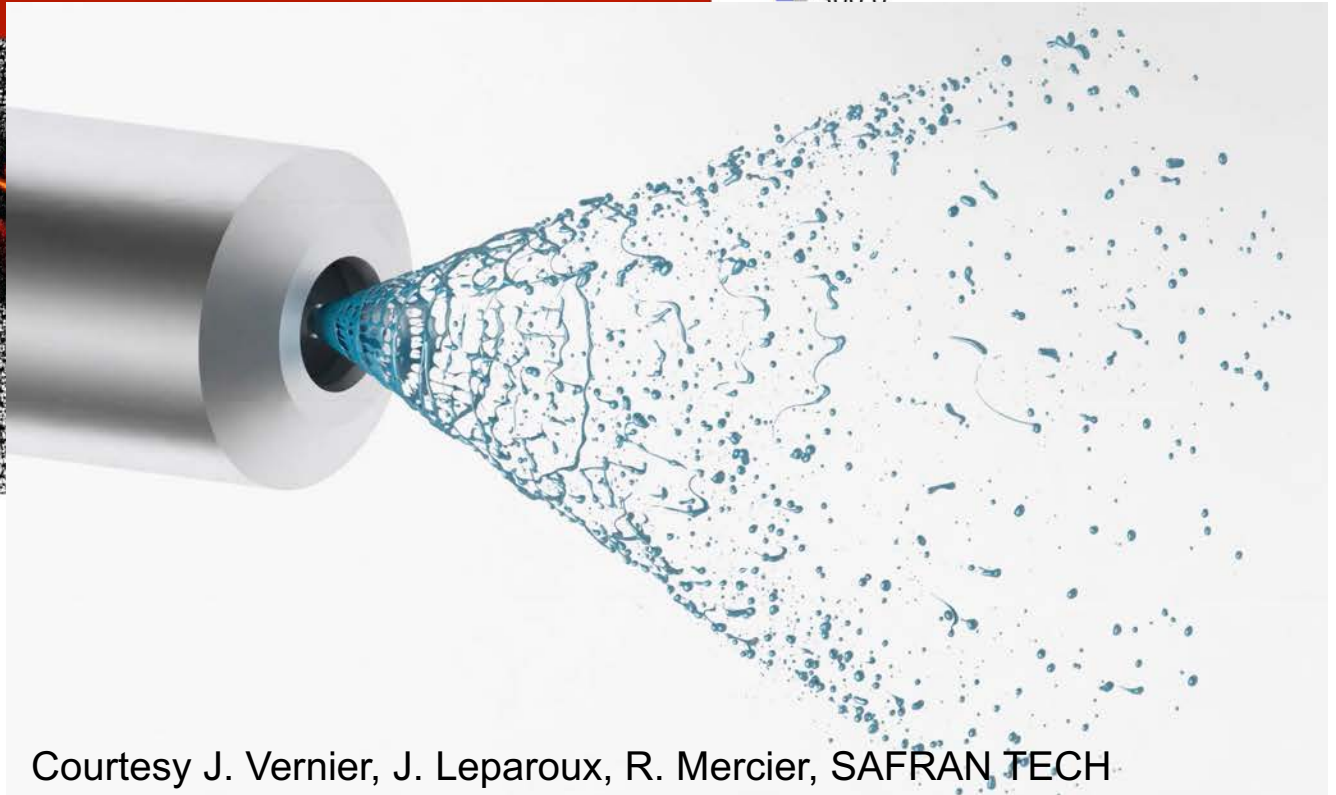
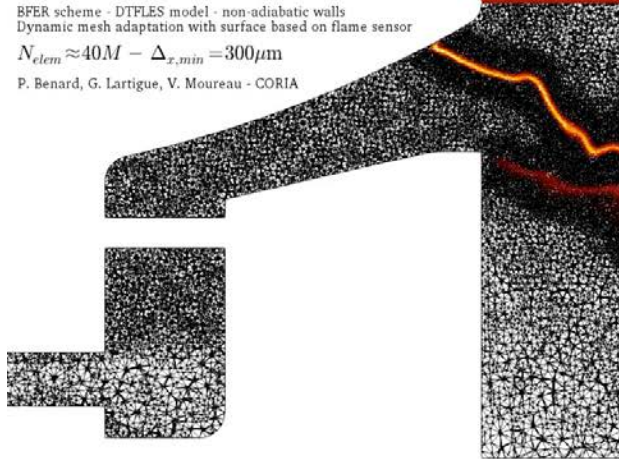
# Motivation

YALES2



## PRECCINSTA burner

BFER scheme - DTFLES model - non-adiabatic walls  
Dynamic mesh adaptation with surface based on flame sensor  
 $N_{elem} \approx 40M - \Delta_{x,min} = 300\mu m$   
P. Benard, G. Lartigue, V. Moureau - CORIA



Courtesy J. Vernier, J. Leparoux, R. Mercier, SAFRAN TECH

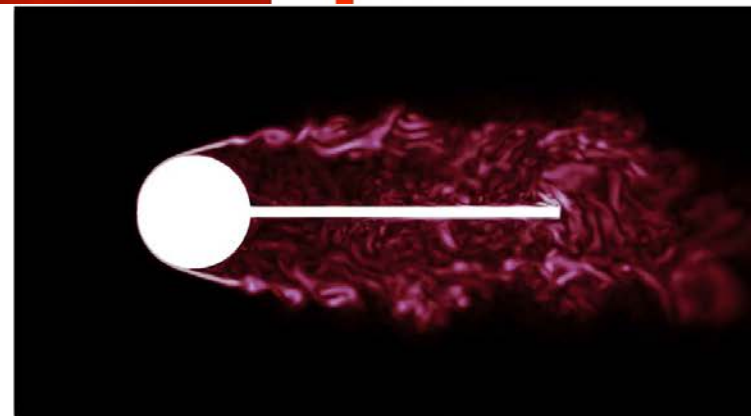
# Motivation

YALES2



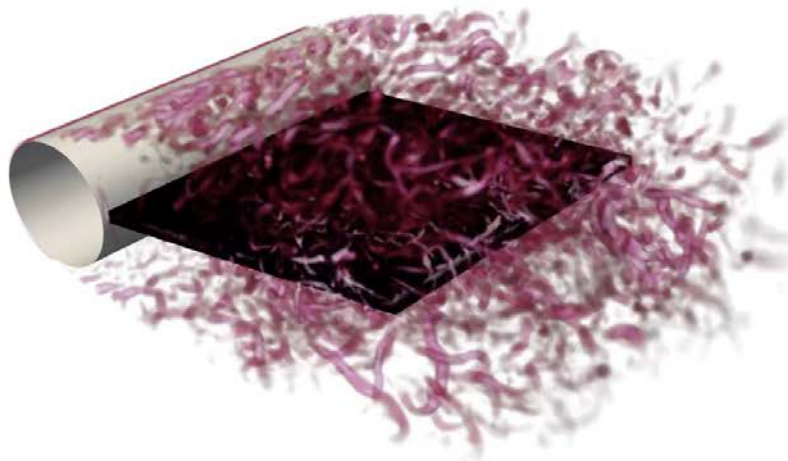
$T$  [K]  
 2200.0  
 2000.0

Q criterion ( $s^{-2}$ )  
 1,0e+5 3,0e+5 5,0e+5 7,0e+5

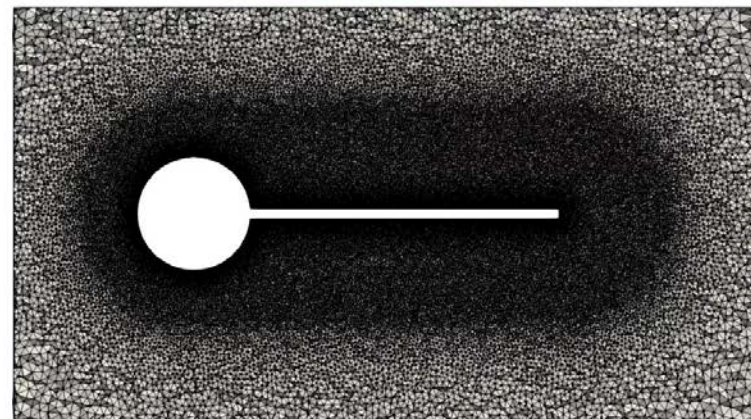


VORTICITY ( $s^{-1}$ )  
 0 200 400 600 800 1000

PREM  
 BFER scheme  
 Dynamic me  
 $N_{elem} \approx 40$   
 P. Benard, G



$|U_y|/D$   
 0 0.1 0.2 0.3 0.4 0.5 0.6



YALES2

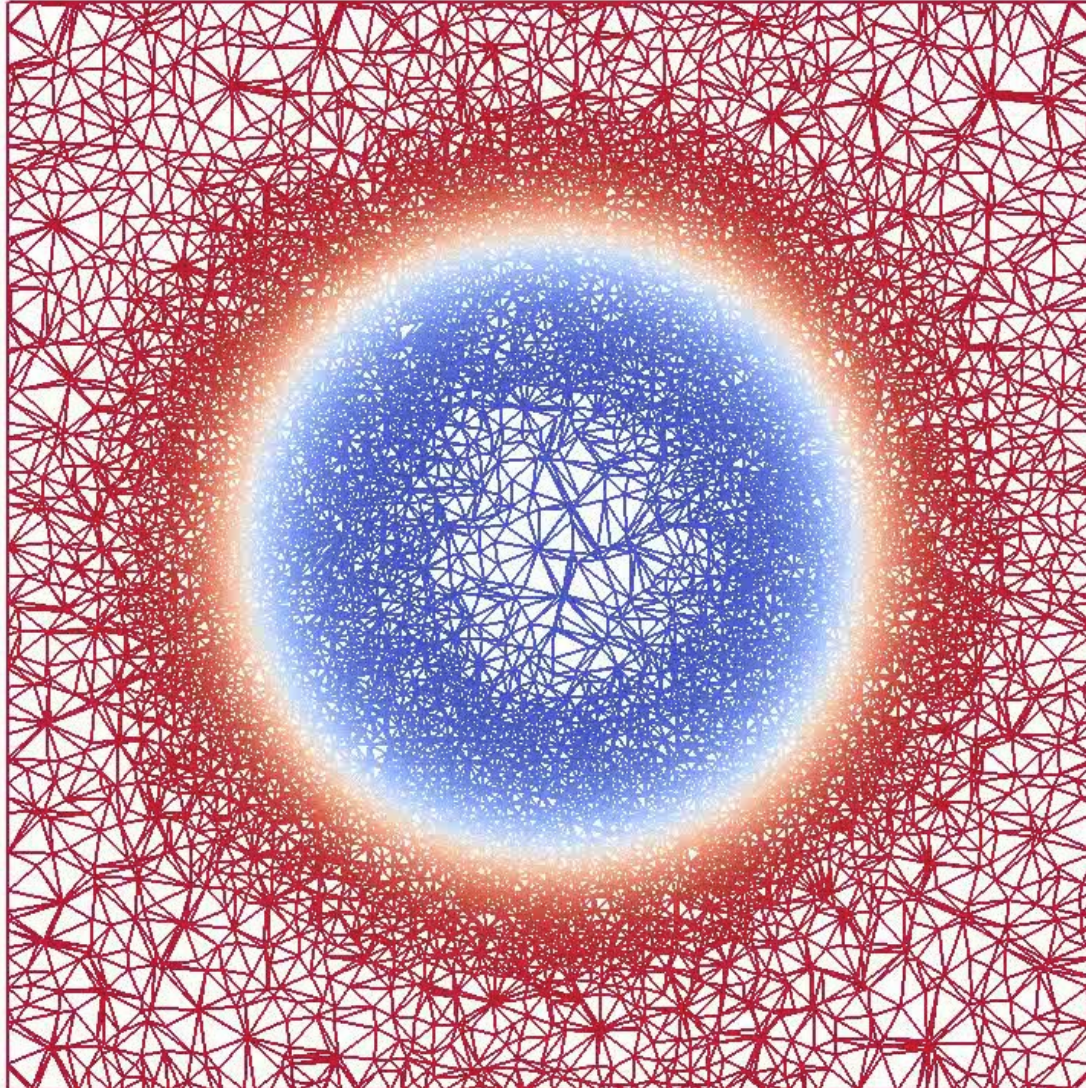
Courtesy J. Vernier, J. Leparoux, R. Mercier, SAFRAN TECH

# Objectives

- To design a **dynamic mesh adaptation** method under constraints:
  - Based on **unstructured grids** for complex geometries
  - Tailored for **distributed-memory** system (10,000+ cores)
  - **Efficient** enough to be called every 10 fluid iterations
  - Compatible with the modeling approach (**finite-volume + LES**)
  - No remeshing at material interfaces to avoid interpolation errors
- Some choices
  - **Isotropic** mesh adaptation (for now)
  - Parallelism handled by the flow solver (interpolation, data transfer)
- A first check if these objectives are reachable for tets
  - Reduced computation cost of fluid solver: **30 to 500  $\mu\text{s}/\text{iter}/\text{node}$**
  - Adaptation of a distributed mesh with **MMG**: **order of 100  $\mu\text{s}/\text{node}$**

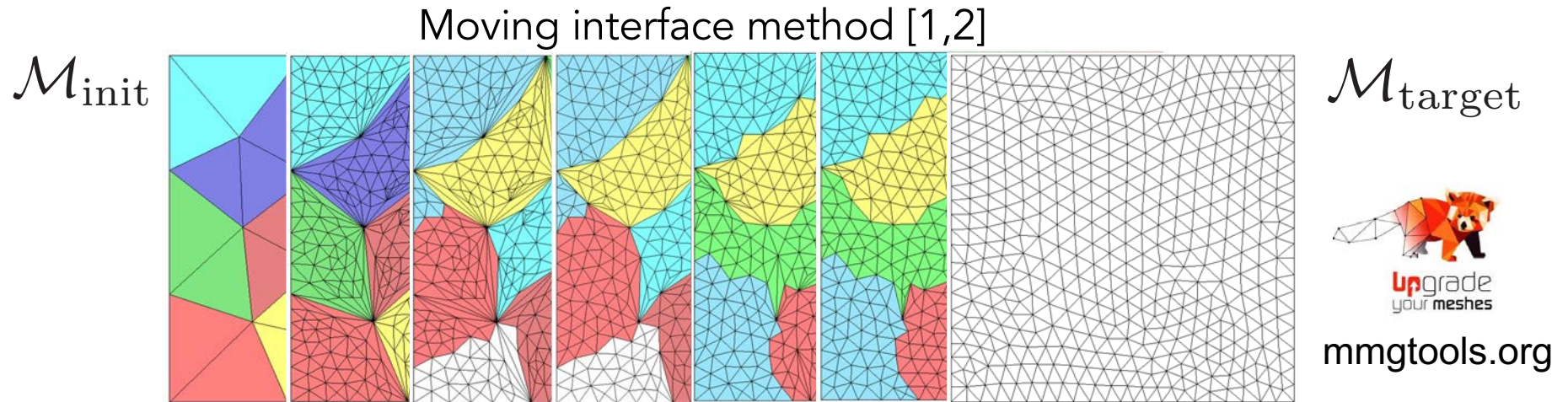
# A first attempt

- January 2015: first use of MMG directly in YALES2

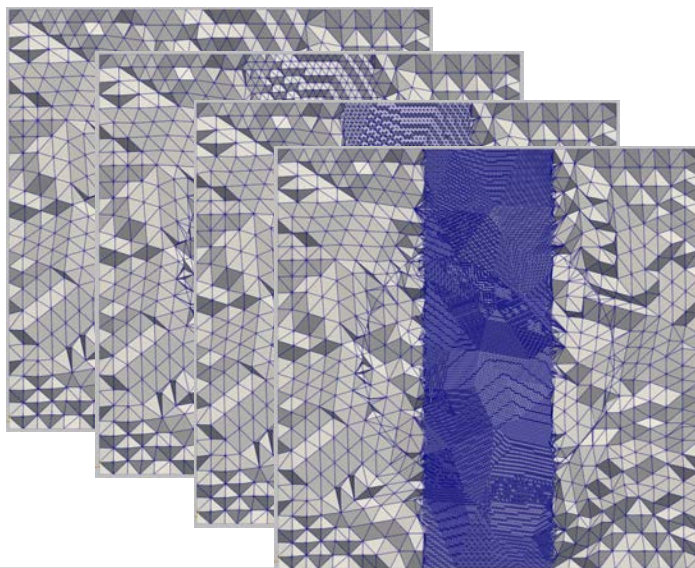


# High-performance dynamic mesh adaptation

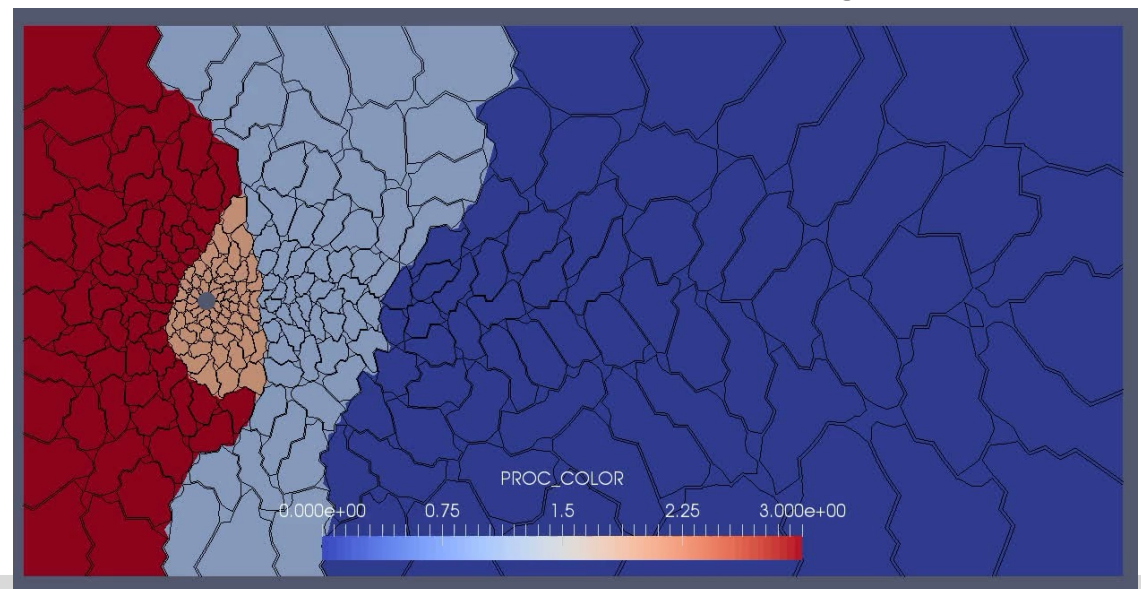
- A combination of several kernels



Parallel edge-cutting



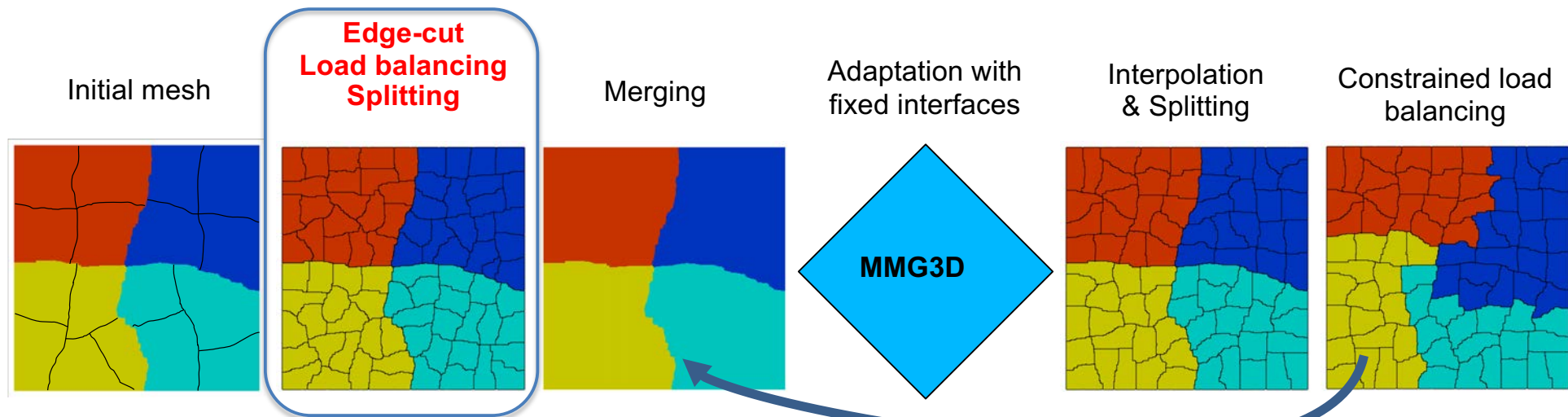
Parallel load-balancing



# High-performance dynamic mesh adaptation

- Full adaptation workflow
  - Example for 4 processors

www.mmgtools.org

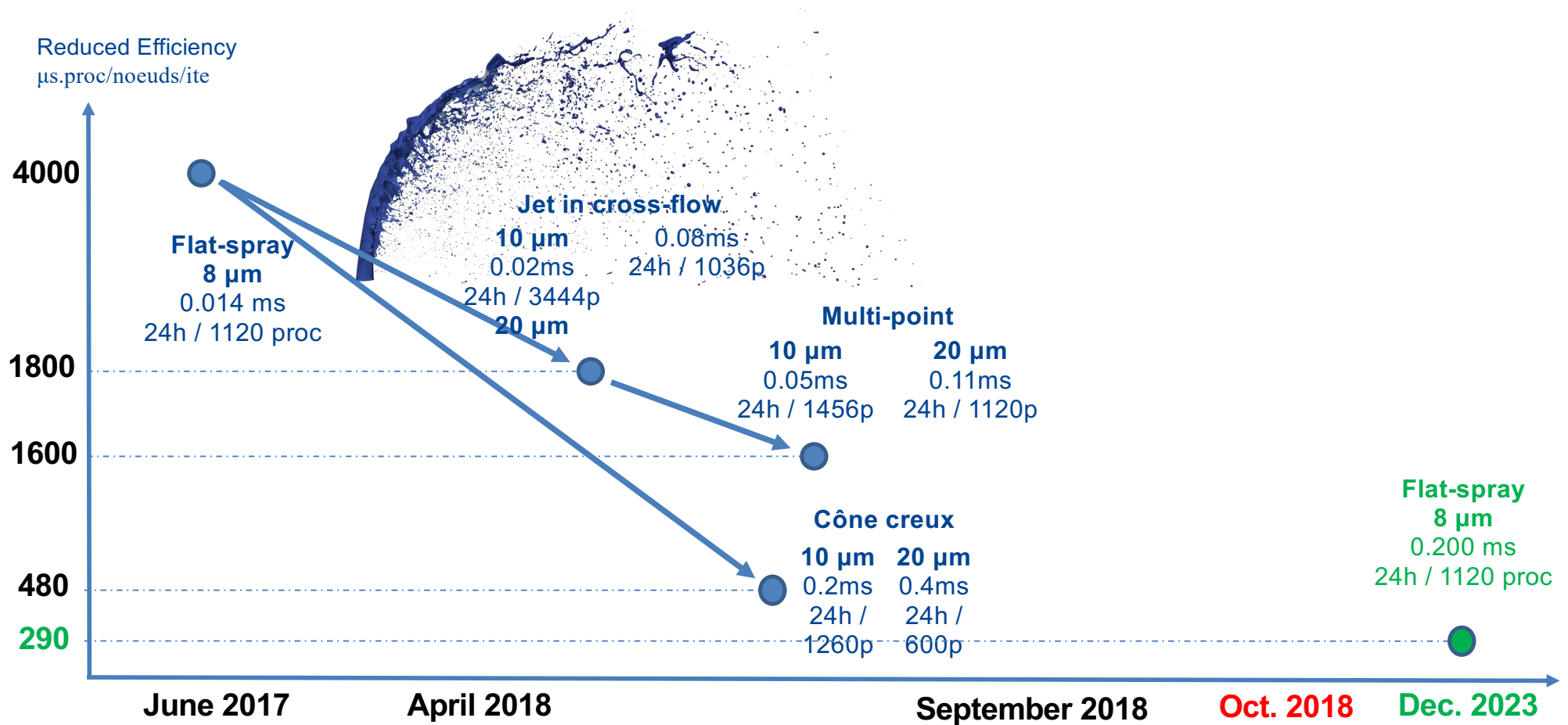


$$\text{if } Sk > Sk_{max} \text{ or } \frac{|\mathcal{M} - \mathcal{M}_{target}|}{\min(\mathcal{M}, \mathcal{M}_{target})} > \epsilon_{\mathcal{M}}$$

- Skewness is the main measure of the mesh quality



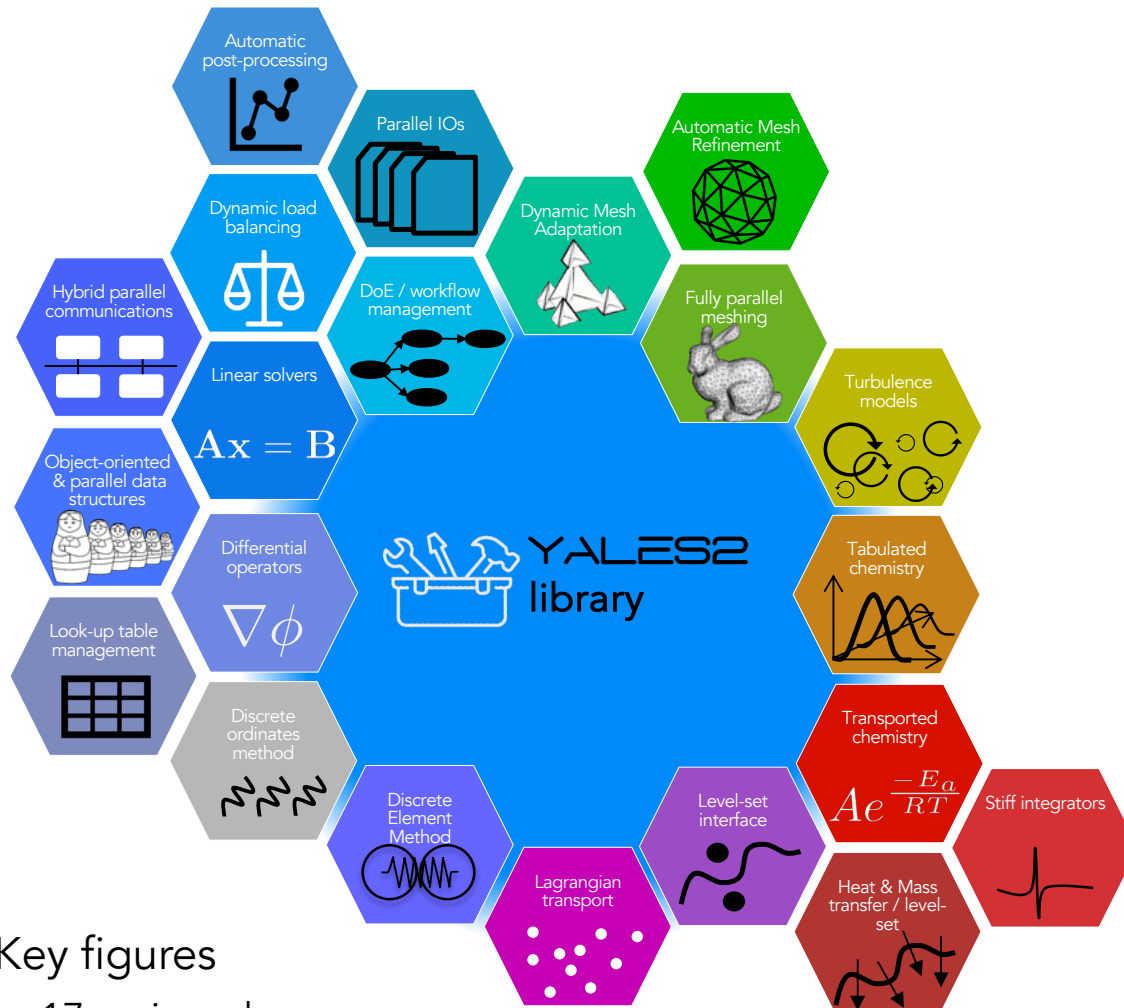
# Performance evolution for atomization problems



Courtesy R. Mercier, SAFRAN TECH

# CFD platform

# The CFD platform



- Key figures

- 17 major releases
- 930 000 object-oriented F2008 lines
- 20 000+ commits
- 10 to 20 commits/day
- 300+ active branches
- 1 200+ merge requests
- 120+ contributors

## YALES2 solvers

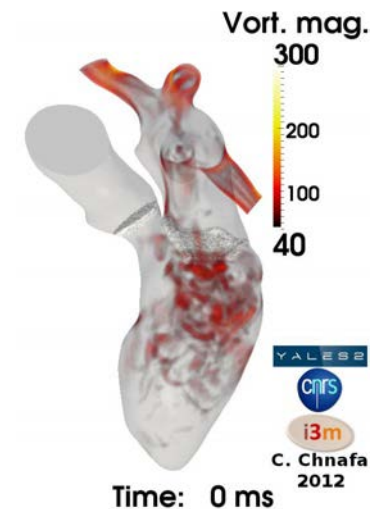
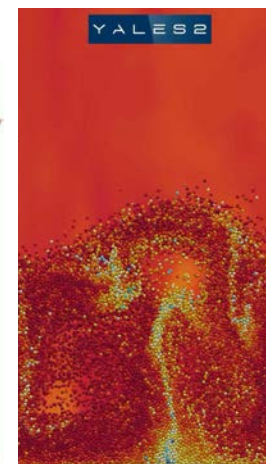
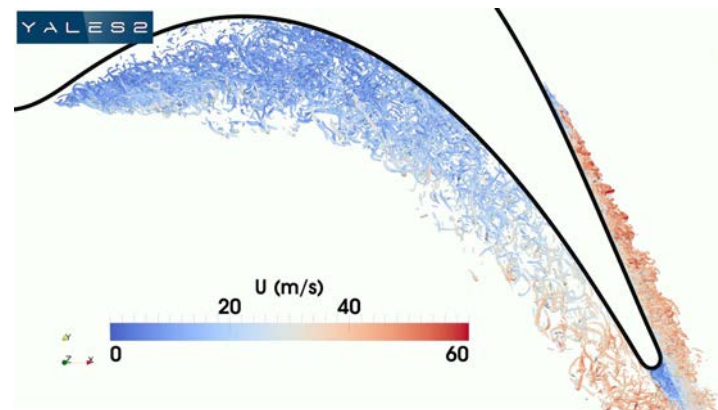
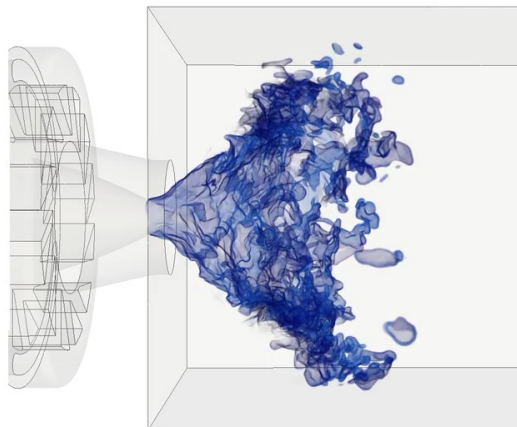
- ICS**  
Incompressible at constant density
- VDS**  
Incompressible at variable density
- SPS**  
Spray with level-set and ghost-fluid method
- ALE**  
Arbitrary Lagrangian Eulerian
- GFS**  
Granular flow with Discrete Element Method
- HTS** Heat transfer
- MHD** Magneto-hydro-dyn
- SMS+FS** Structural mech.
- ACS** Acoustics
- BOI** Boiling
- ECS** Compressible flow

## YALES2 features

- High fidelity
- Multiphysics
- High performance

# CFD platform: YALES2

- Features
  - **Unstructured meshes** and **adaptive grid refinement**
  - Low-Mach number Navier-Stokes equations (incompressible and variable density)
  - **4-level domain decomposition** [3] and hybrid OpenMP/MPI communications
  - Highly efficient solvers for linear system inversion (PCG, DPCG) [4]
  - 4th-order central **finite-volume method** and 4th-order time integration
  - Two-phase flows (Lagrangian particles), **spray and atomization** (Levelset)
  - Combustion modeling (Tabulated or **finite-rate chemistry**, NOx model, ...)
  - Suited for massively parallel computing (>32 000 procs)



# The YALES2 network

- Developed by CORIA, the French Combustion Community and others
  - 600+ researchers/engineers trained at CORIA since 2009
  - 200+ articles (Google Scholar)
- A unique network to ease collaboration and disseminate numerics, algorithms and models to the community

## *Academic partners*

CORIA, IMAG, LEGI, EM2C, IMFT  
CERFACS, ONERA, IFP-EN, LMA, LJK  
LOMC, PPRIME, LMB/INRIA, ICARE  
ULB, UMONS, UCL, VUB, TU DELFT  
CORNELL U., VERMONT U.  
SHERBROOKE U.

## *HPC centers*

CRIANN, IDRIS, CINES, TGCC  
ROMEO, GENCI, PRACE

## *Industrial partners*

SAFRAN  
ARIANE GROUP  
GE HYDRO  
SIEMENS/GAMESA  
AIR LIQUIDE  
TOTAL ENERGIES  
...

## *HPC experts*

INTEL/CEA/GENCI/UVSQ, HPE  
ATOS, IBM, AMD, NVIDIA

## *SMEs*

GDTech  
YPSO FACTO

The logo for YALES2, consisting of the letters Y, A, L, E, S, 2 in a white, sans-serif font on a dark blue rectangular background. The entire logo is enclosed within a large, hand-drawn black oval.

[www.coria-cfd.fr](http://www.coria-cfd.fr)

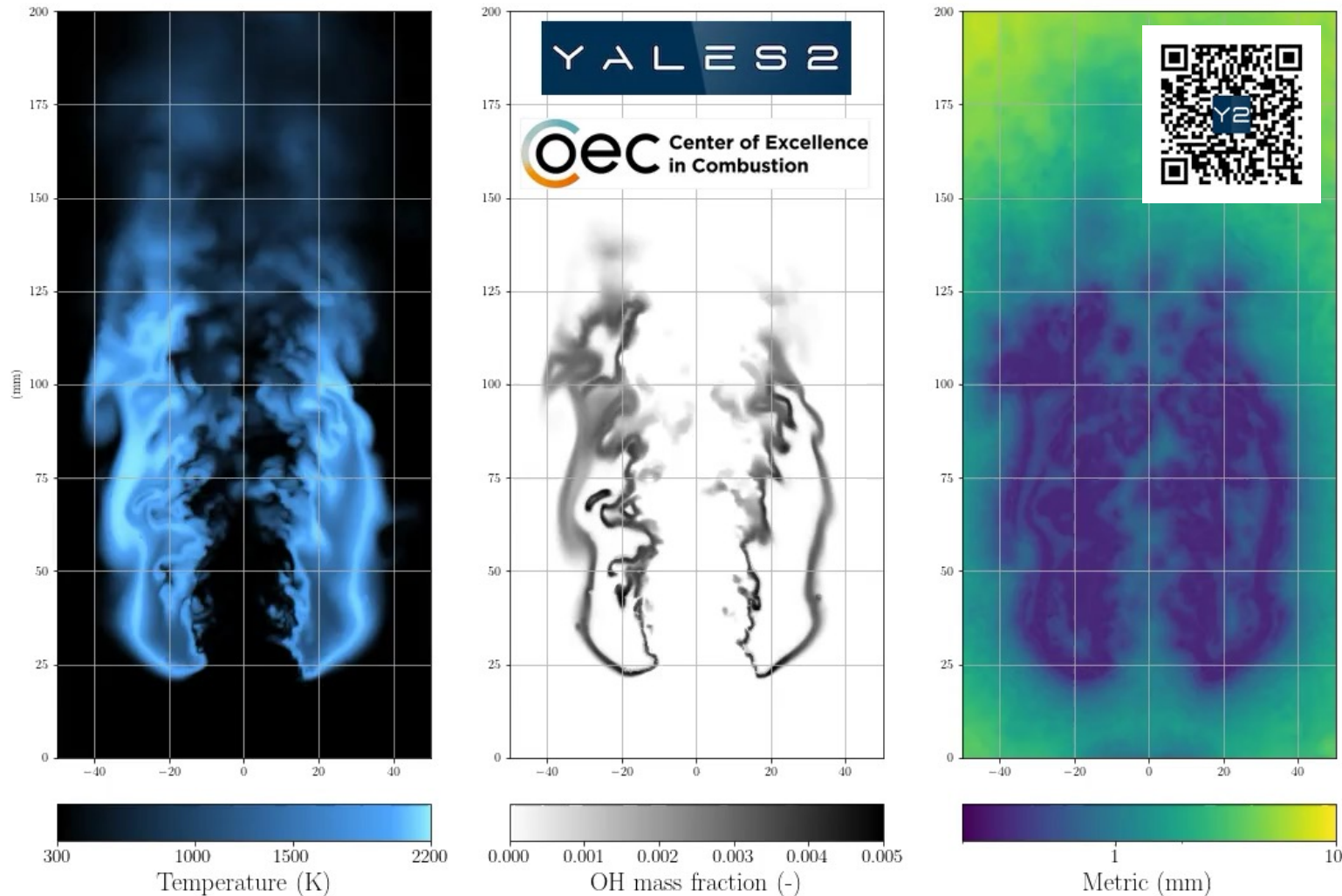
# The YALES2 network



# A few applications

# DMA of spray combustion

- LES simulations with finite-rate chemistry using dynamic adaptive mesh refinement.
  - Chemistry: ARC for n-heptane (CERFACS), 25 species, 210 reactions
  - Spray: Lagrangian Particle with dynamic load balancing (Stock et al., IJNMF 2023)



$\Delta x_{min} = 200 \mu m,$   
300M cells  
10,000 cores  
Jean-Zay @  
IDRIS

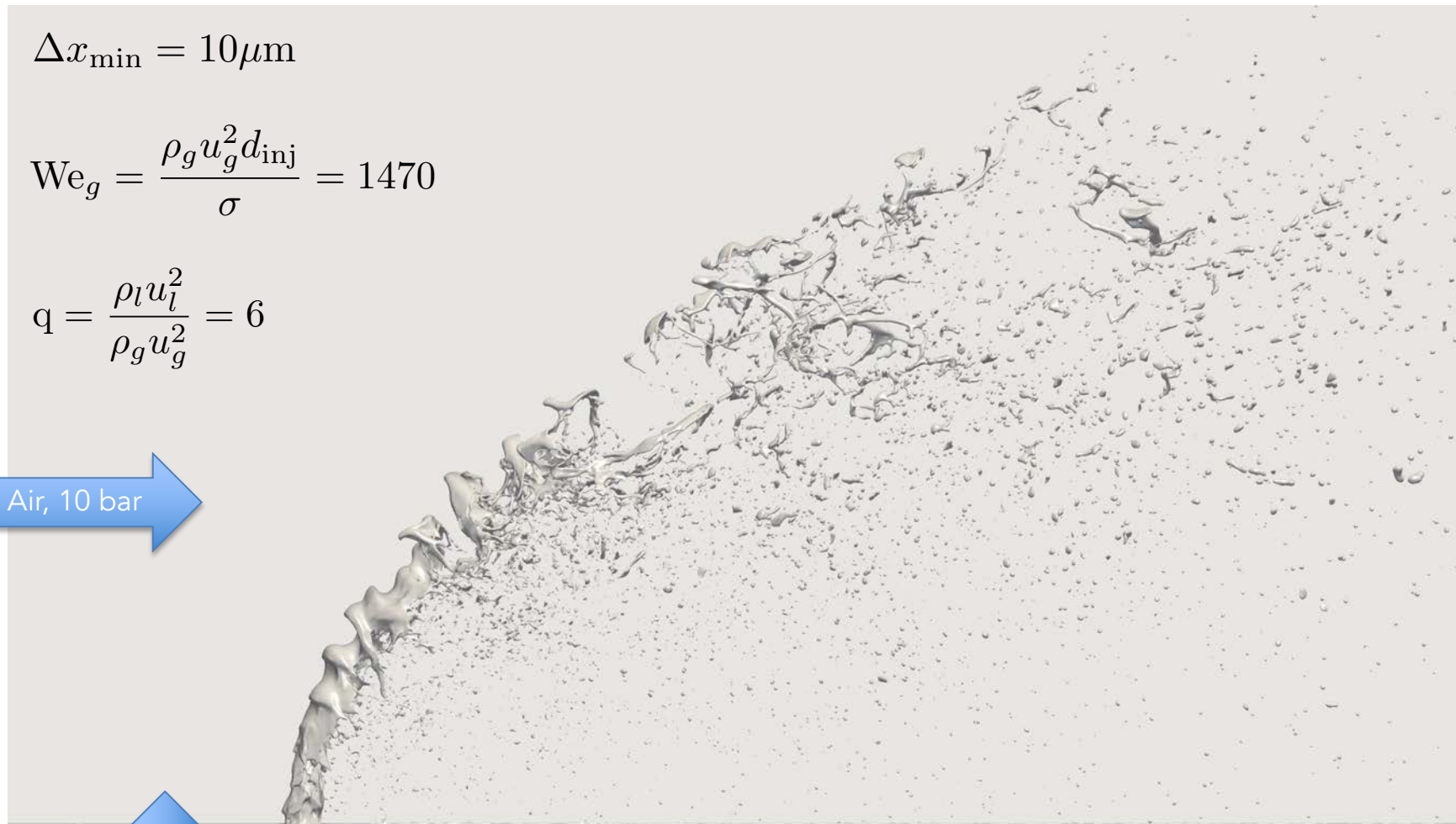


# DLR jet-in-cross-flow [1]

$$\Delta x_{\min} = 10 \mu\text{m}$$

$$\text{We}_g = \frac{\rho_g u_g^2 d_{\text{inj}}}{\sigma} = 1470$$

$$q = \frac{\rho_l u_l^2}{\rho_g u_g^2} = 6$$



R. Janodet<sup>a,b</sup>, C. Guillamón<sup>b</sup>, V. Moureau<sup>a</sup>, R. Mercier<sup>b</sup>,  
G. Lartigue<sup>a</sup>, P. Bénard<sup>a</sup>, T. Ménard<sup>a</sup>, A. Berlemont<sup>a</sup>

<sup>a</sup>CORIA, CNRS UMR6614, INSA and University of Rouen, France

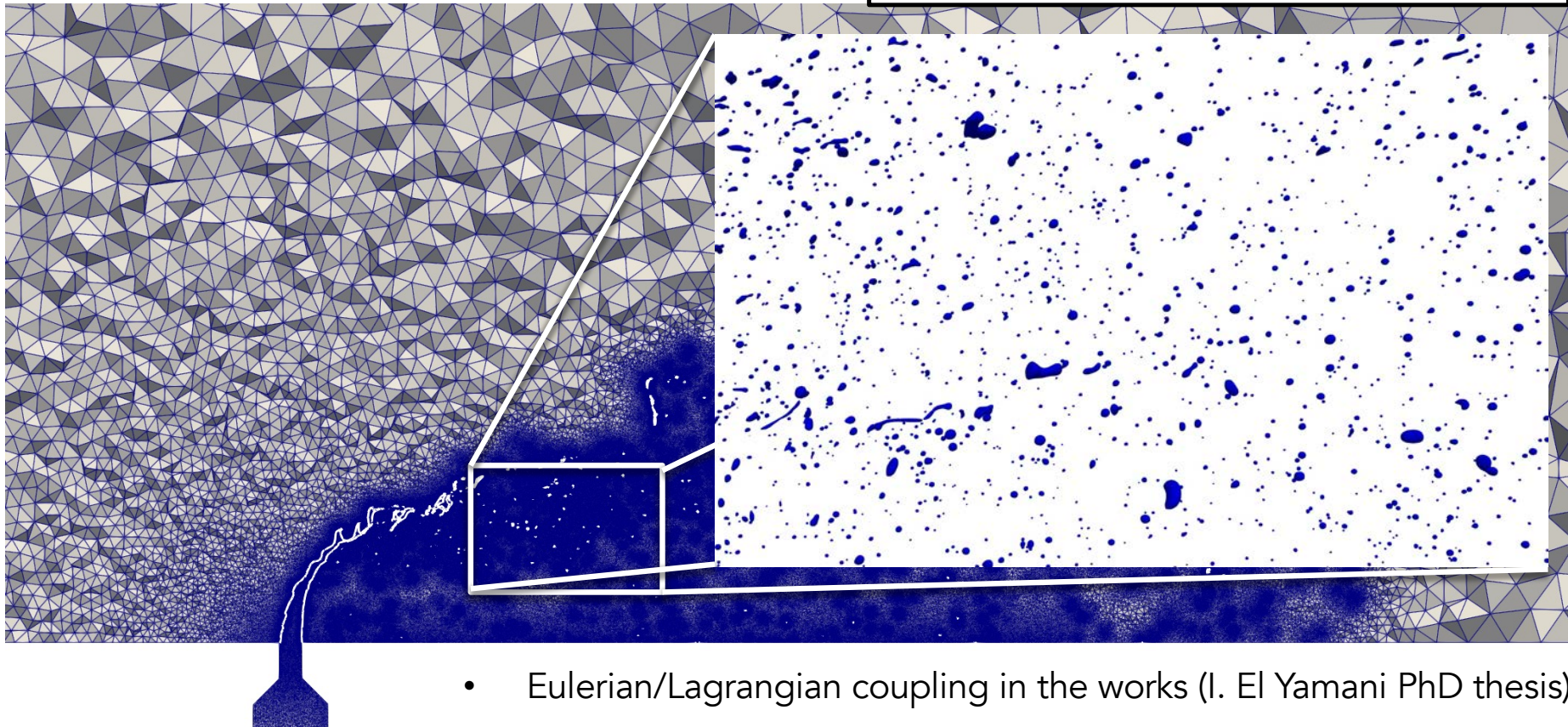
<sup>b</sup>Safran Tech, Rue des Jeunes Bois, Chateaufort, 78114 Magny-Les-Hameaux, France



# DLR jet-in-cross-flow [1]

- Flow topology analysis

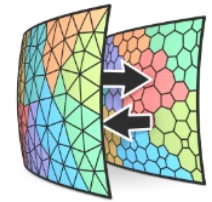
$\Delta x = 10 \mu m$ , 1B cells, 15 600 liquid structures  
10 000 cores of Irene AMD, TGCC, CEA



- Eulerian/Lagrangian coupling in the works (I. El Yamani PhD thesis)

# Modeling of fire resistance tests for composite materials

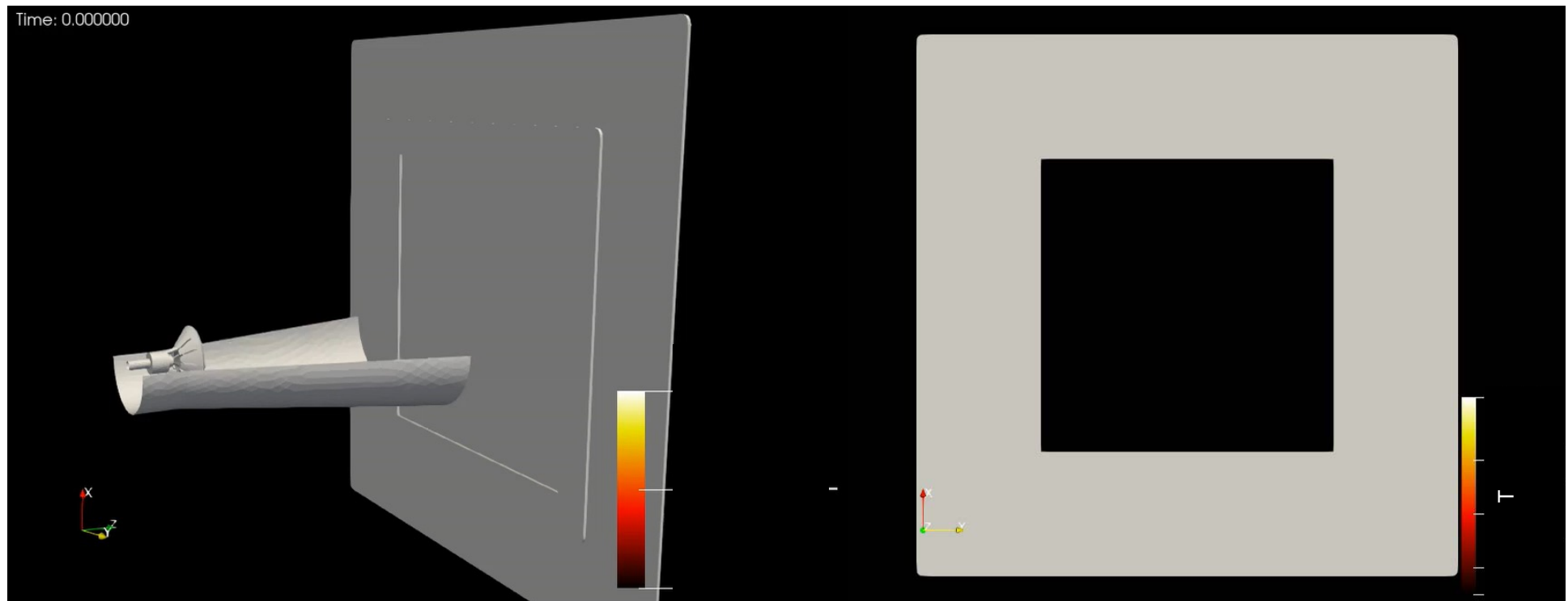
- Kerosene spray burner
  - BFER mechanism for kerosene, 6 species, 2 reactions
- Coupling of 3 solvers
  - combustion, conduction, radiative heat transfer (Discrete Ordinate Method)



**CWIPi**

**ONERA**

THE FRENCH AEROSPACE LAB



Courtesy R. Letournel, SAFRAN TECH

# Wind turbines

- Impact of yaw on wake development behind offshore wind turbines
- Collaboration with SIEMENS/GAMESA Renewable Energies

$t = 0.00 \text{ s}$

YALES2

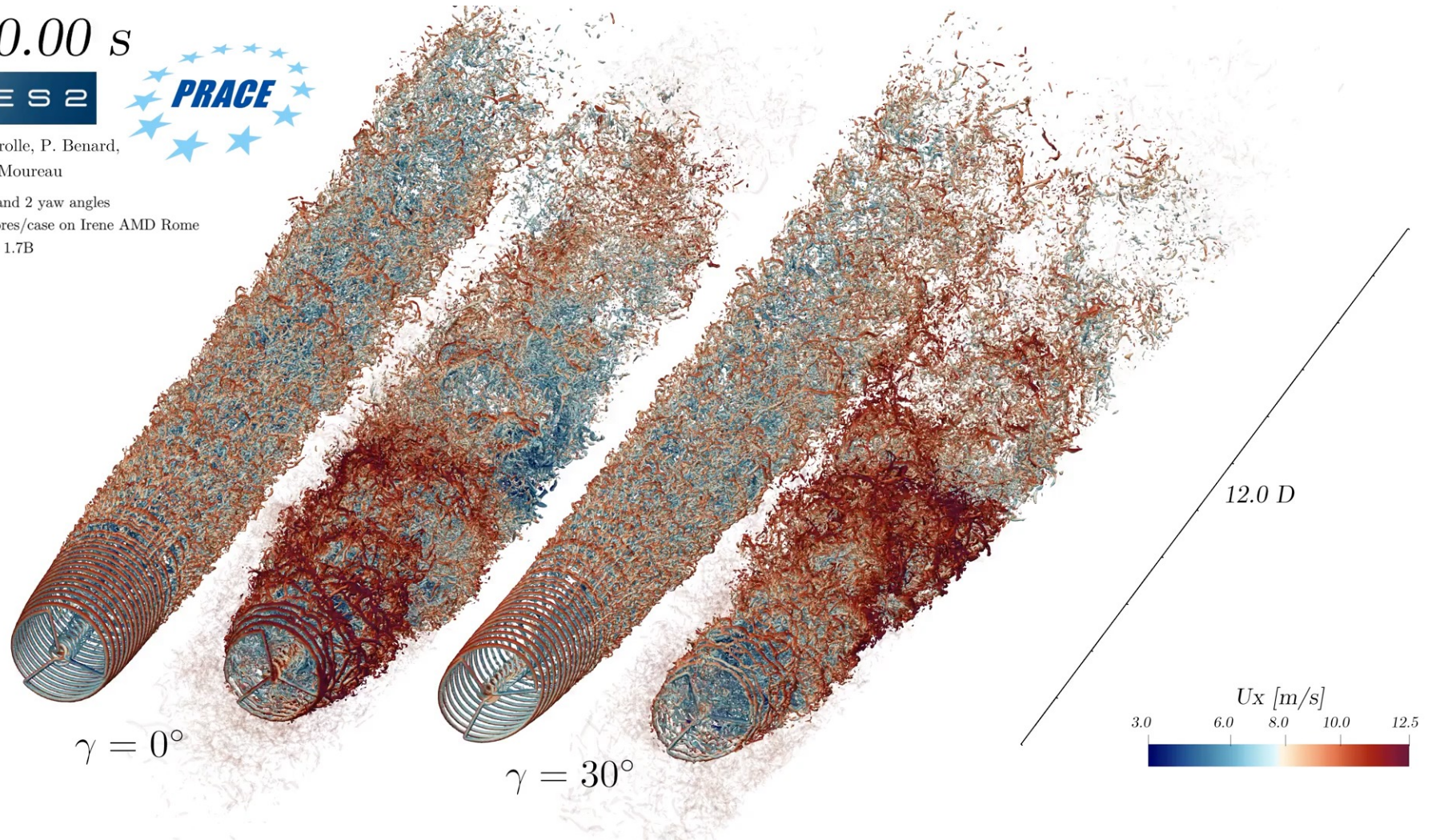


F. Houtin Mongrolle, P. Benard,  
G. Lartigue, V. Moureau

4 cases: 2 inflows and 2 yaw angles

Resources: 8448 cores/case on Irene AMD Rome

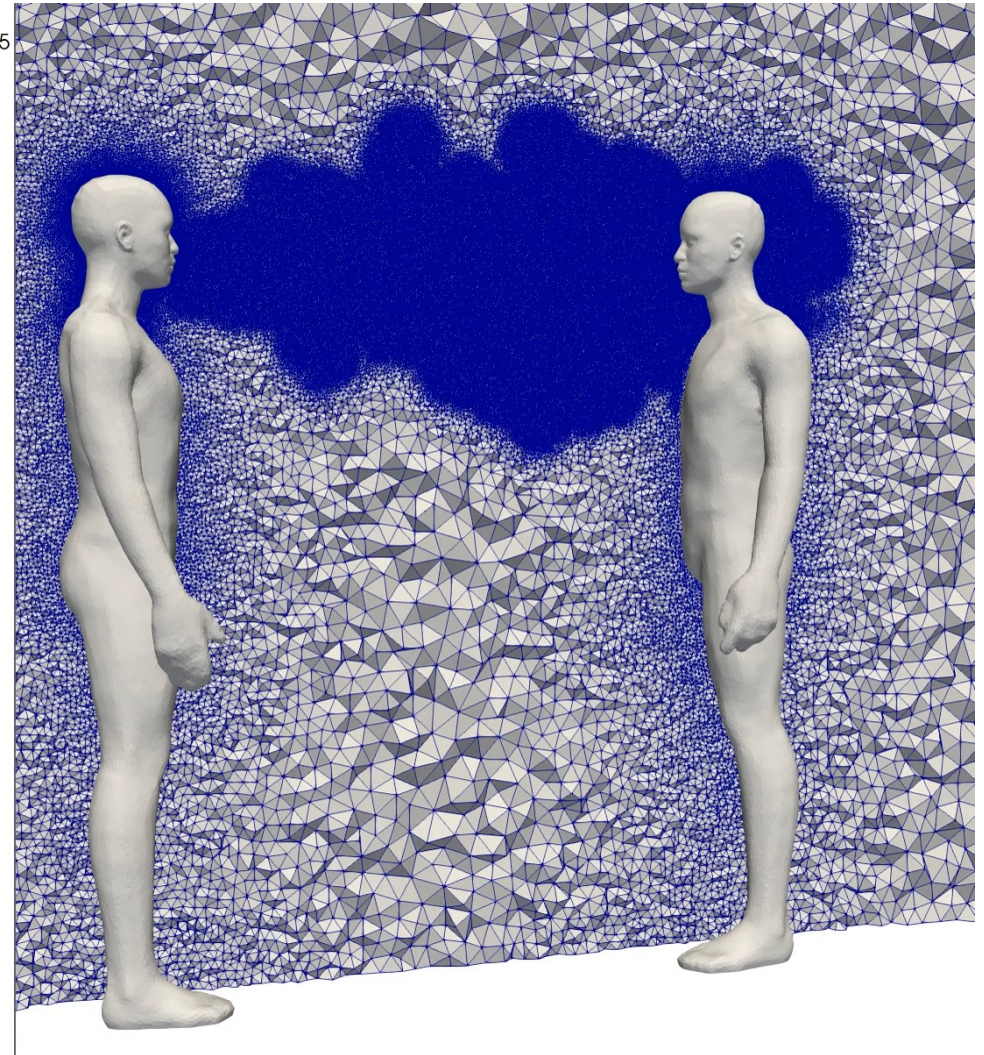
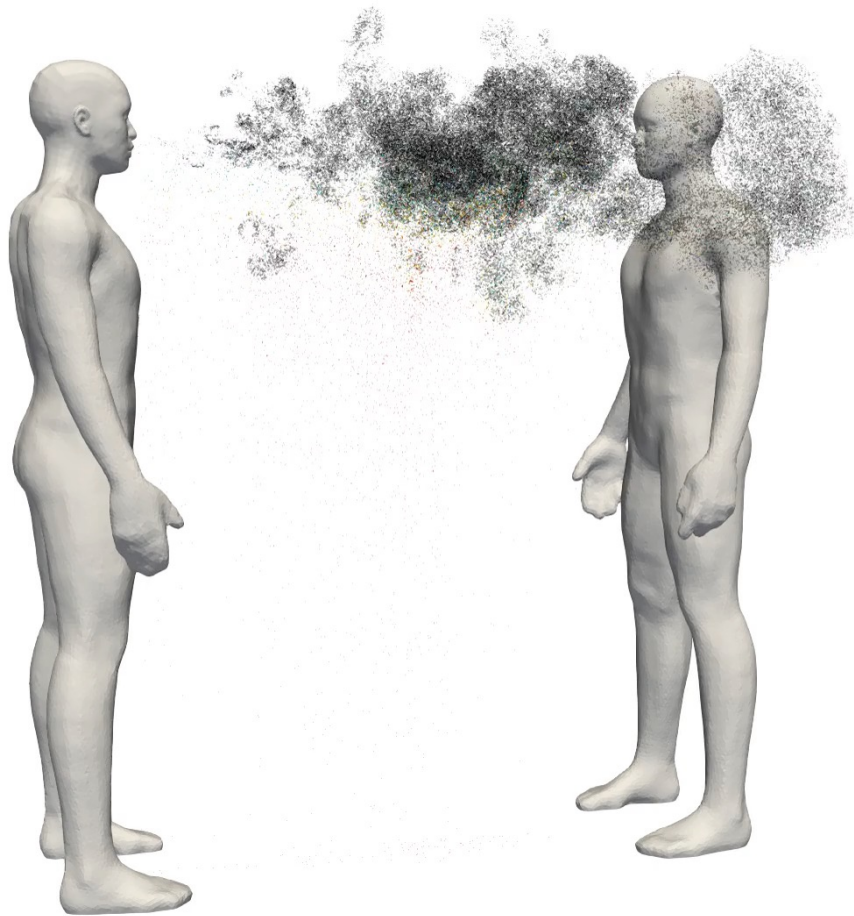
Mesh sizes: 1.5B – 1.7B



# Simulations in the framework of the COVID pandemic

Time: 3.000498

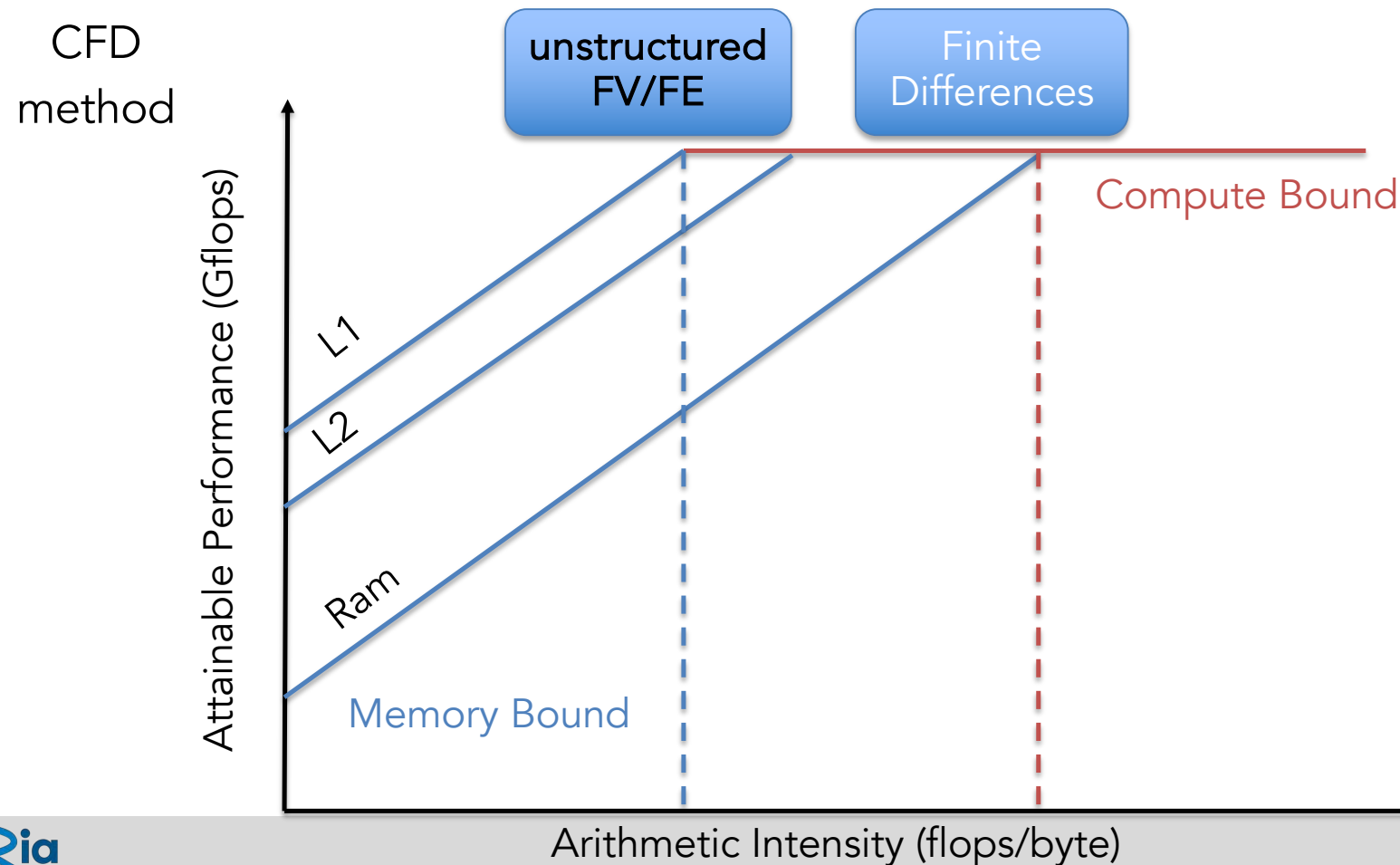
Droplet diameter  
1.0e-07 1e-5 2e-5 3e-5 4e-5 5.0e-05



# Performance optimization

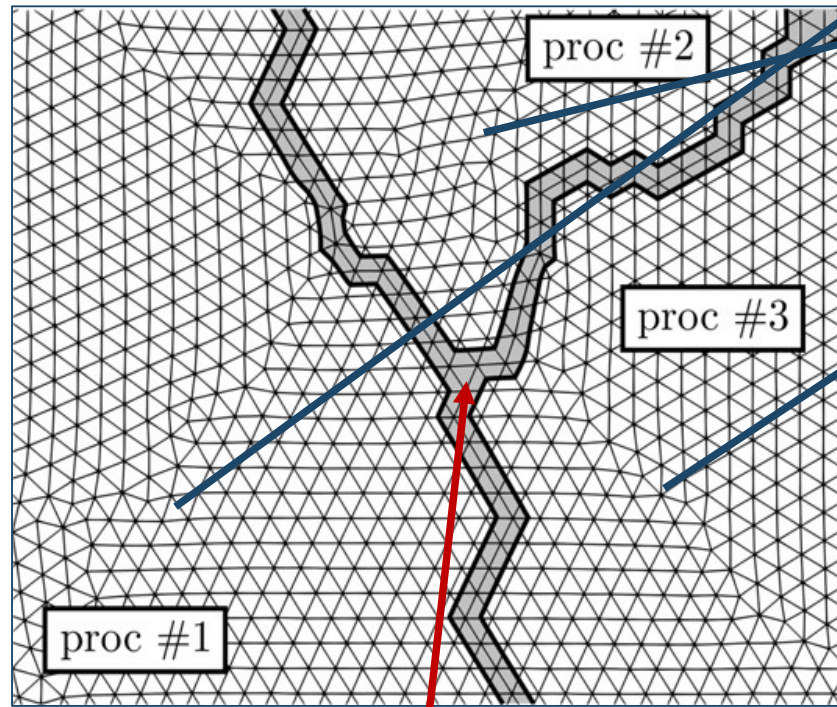
# Importance of memory accesses in unstructured FV codes

- Code performance on a CPU can be limited by:
  - Processor speed (compute bound)
  - **Memory access speed** (memory bound)
  - The roofline model

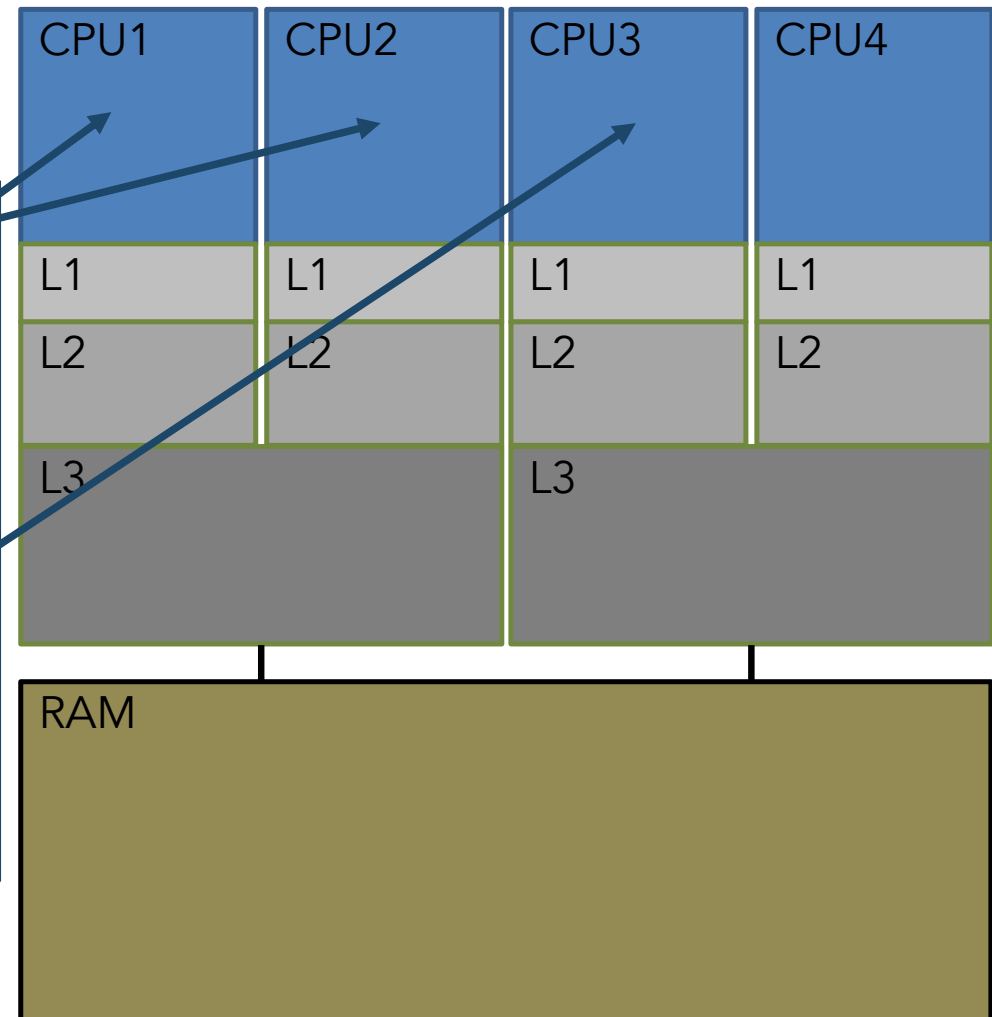


# CPU: Parallel computation and domain decomposition

- Large problems can not be computed by a single process
- Domain decomposition to divide the problem amongst many processes
  - More memory available
  - More computational power
  - Communication needed



Data on these nodes have to be exchanged between processes

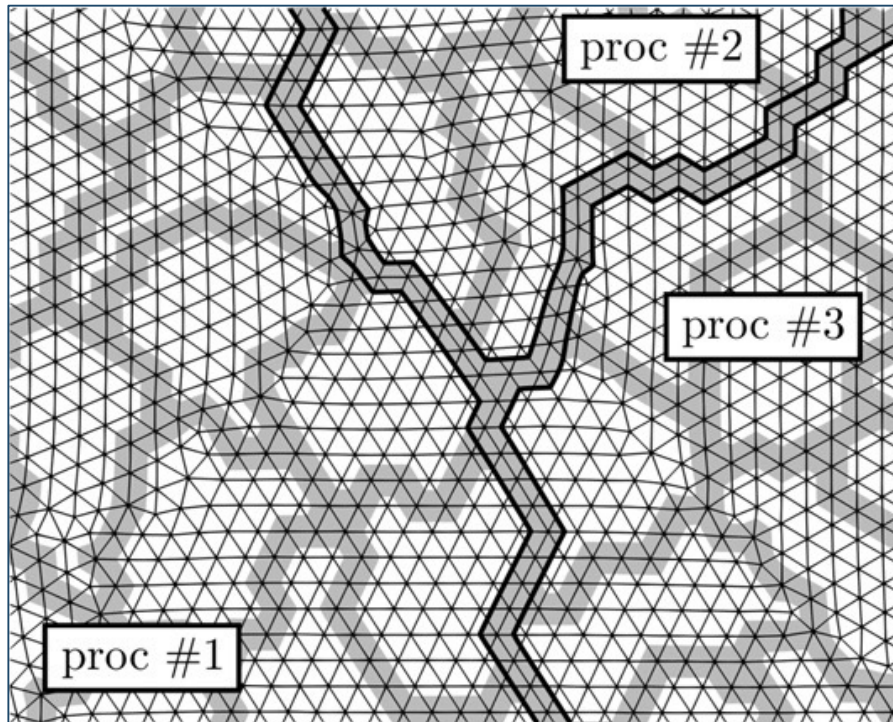




# MPI/OpenMP + cache-blocking: 3-level domain decomposition

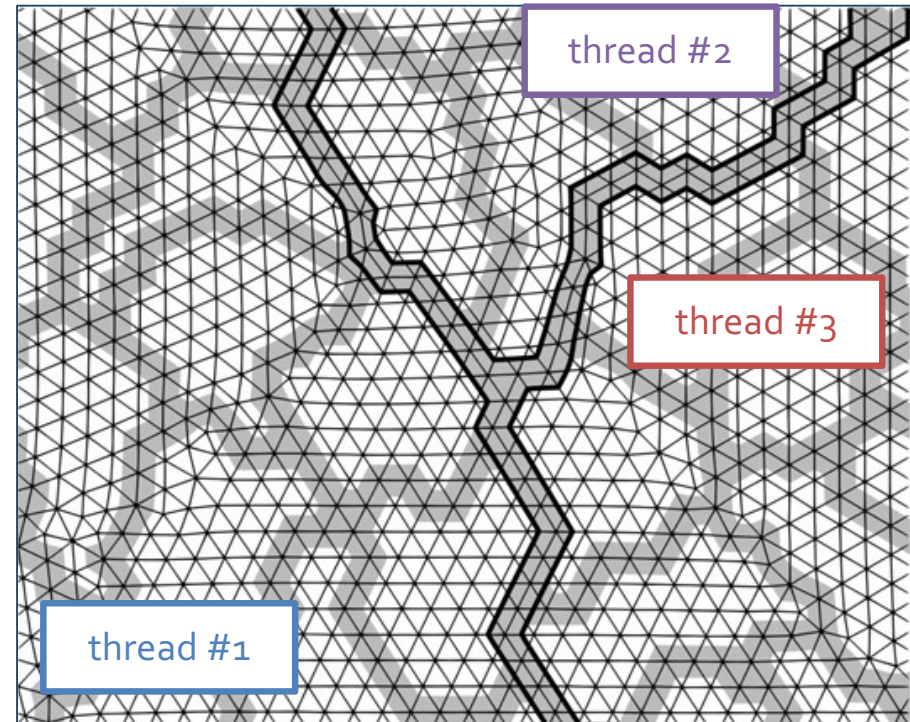
## MPI + OpenMP + in-thread domain decomposition

Full MPI [1]



- Cell groups for cache-blocking
- Cell group size ~ 2000
- **Overhead: node duplication**

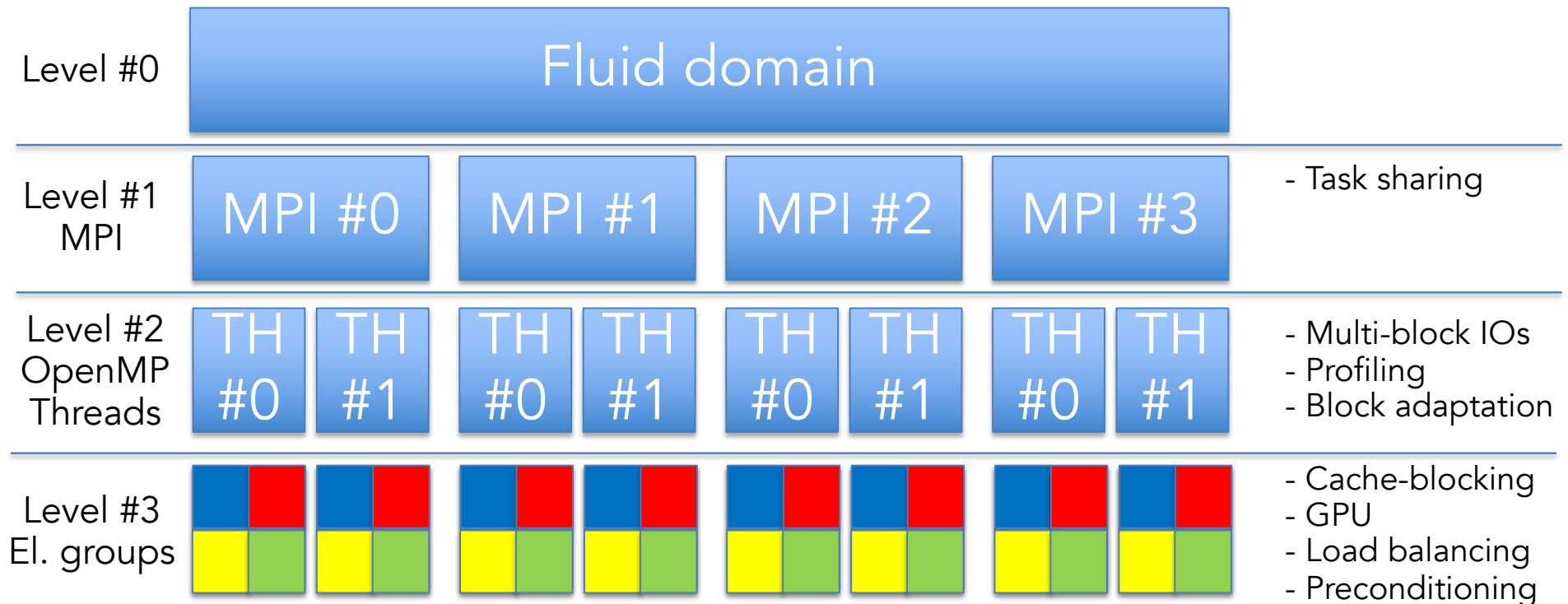
Coarse-grain Hybrid OpenMP + MPI



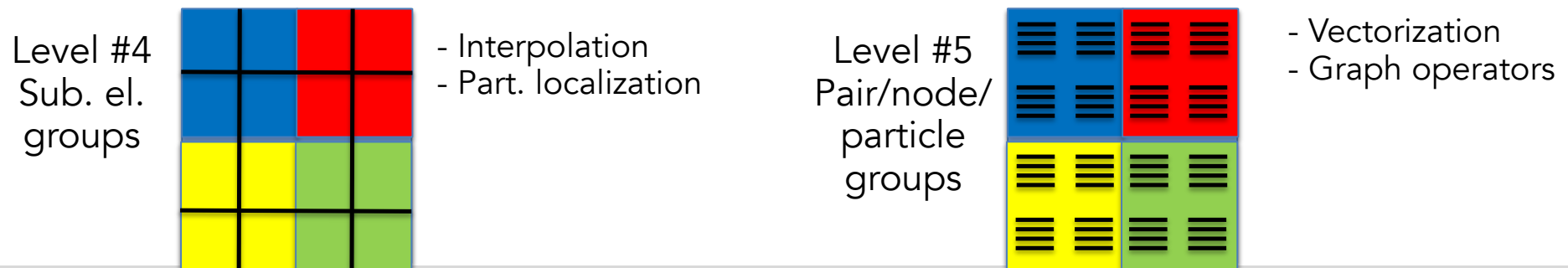
- Threads substitute MPI ranks
- Fewer MPI ranks but thread-safety
- Overhead:
  - Threads must communicate
  - Node duplication

# Hierarchical domain decomposition in YALES2

- Explicit partitioning

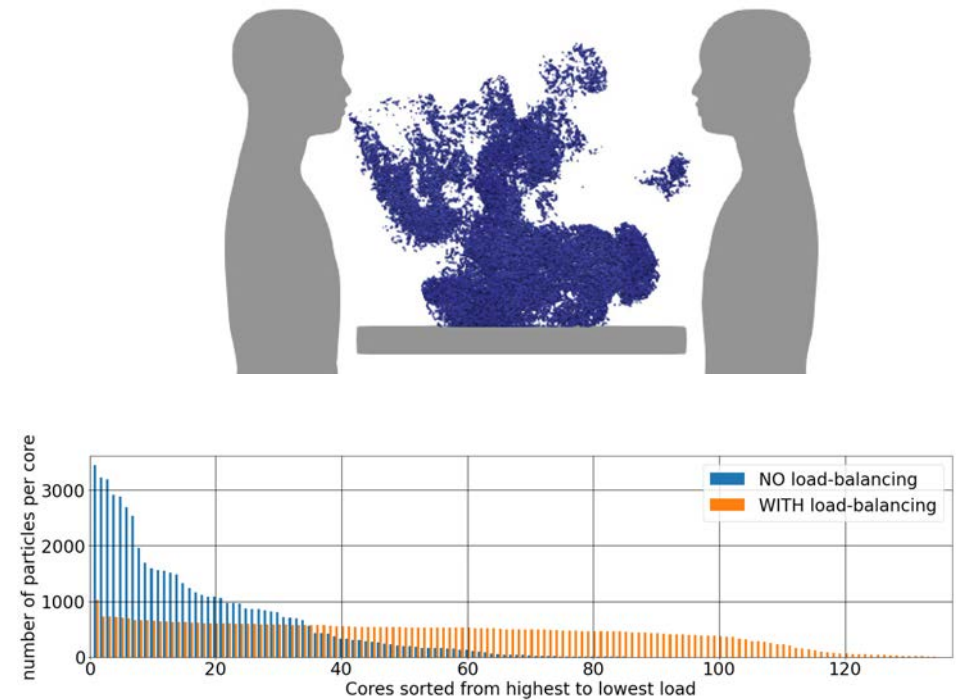
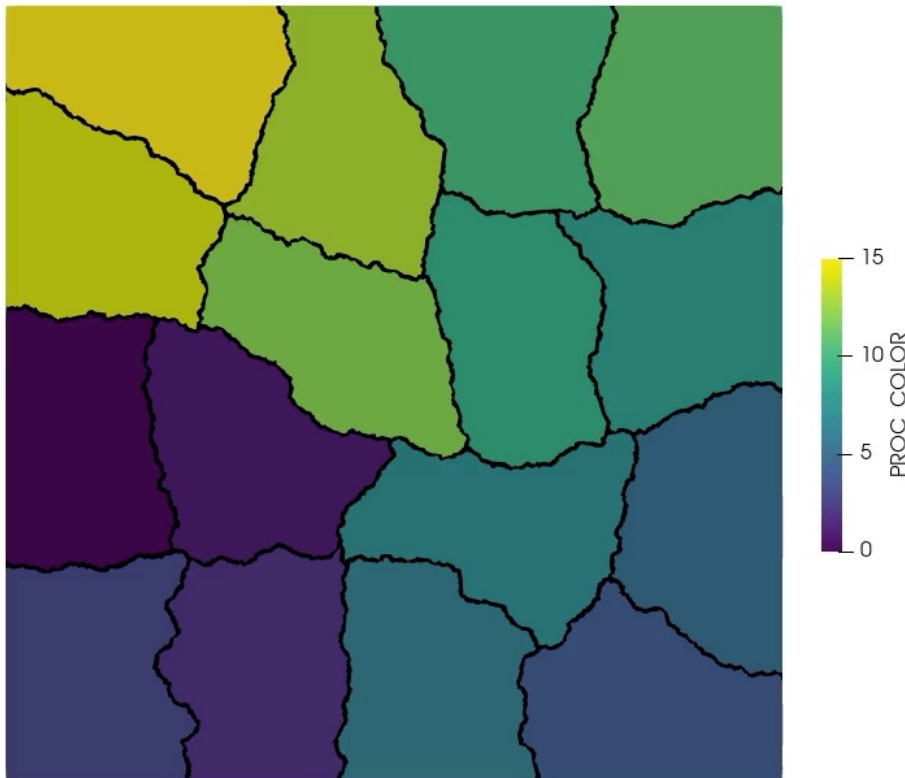


- Implicit partitioning

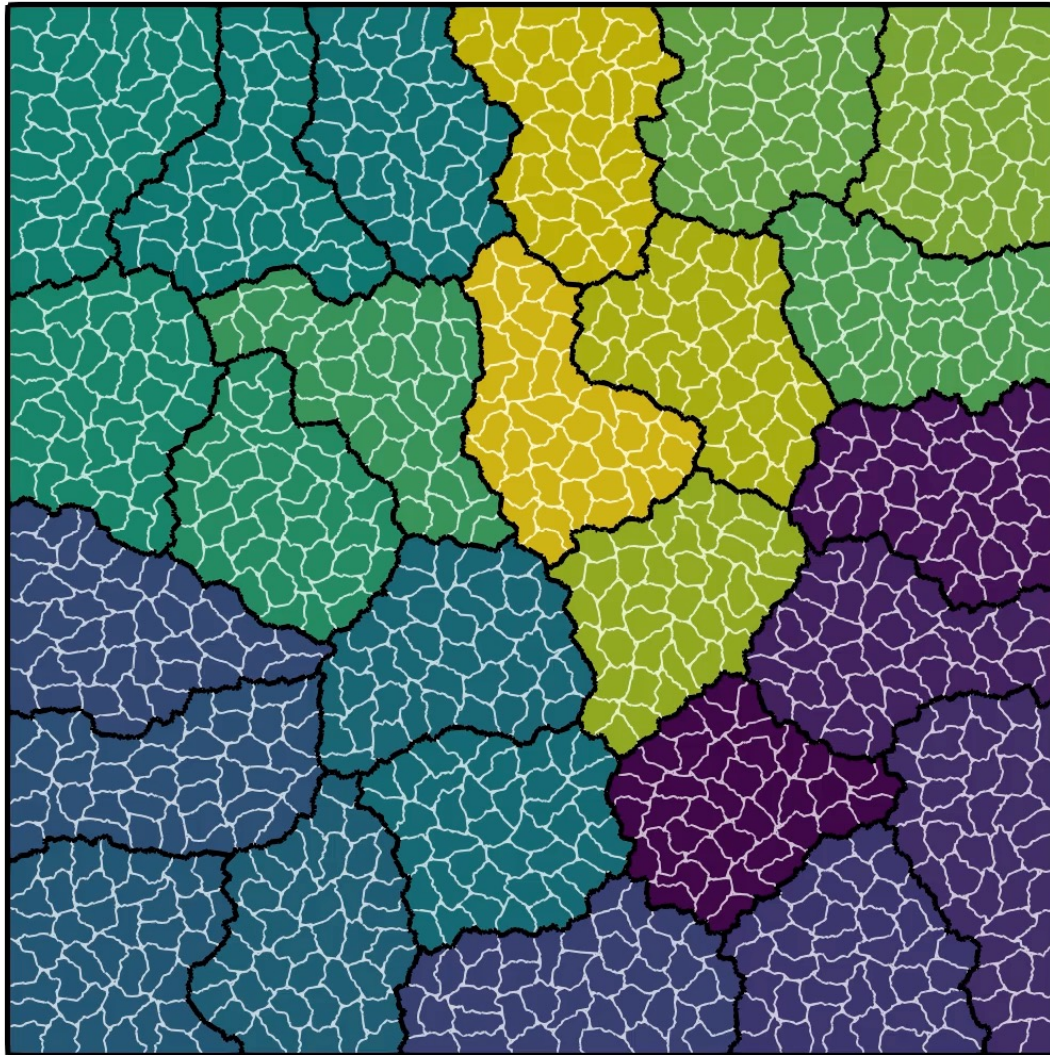


# Dynamic load balancing for Euler/Lagrange models

- A difficult task which requires: mesh coloring, data movement, ...
- Balancing cells and particles requires 2-constraints optimization [1]



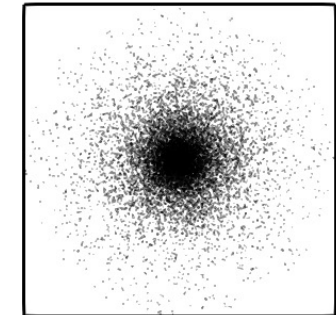
# Dynamic load balancing for Euler/Lagrange models



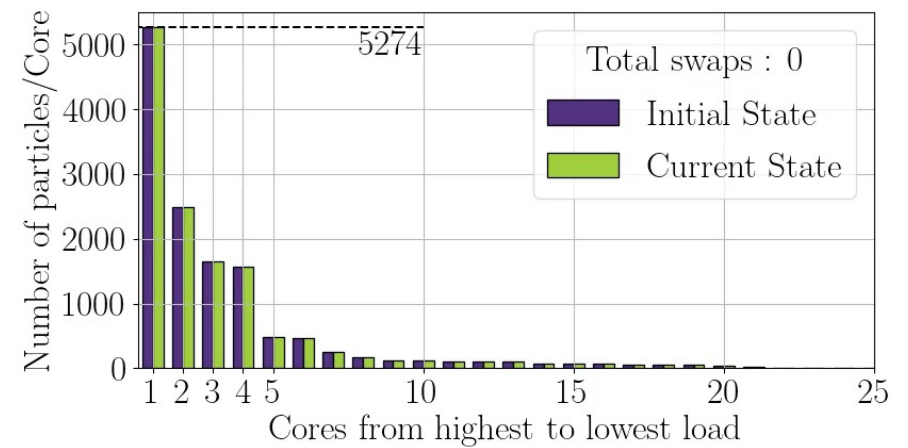
A. Stock, G. Lartigue,  
V. Moureau



A core and  
its swappable subparts



Lagrangian particle  
distribution



# GPUs & APUs

- Working on OpenACC port since 2017
  - Benefits from array objects (r1\_t, r2\_t, ..., i1\_t, i2\_t, ...)
  - GPU memory management in the data structures

```
!=====
!# <STRUCTURE NAME=r2_t>
!# <DESCRIPTION>Pointer for two-dimension real variables.</DESCRIPTION>
type r2_t
  real(WP), allocatable :: val(:, :) !# <VAR NAME=val TYPE=real(:, :)>Values</VAR>
  character(len = LEN_MAX) :: name !# <VAR NAME=name TYPE=character>Name of the pointer</VAR>
  integer :: name_len !# <VAR NAME=name_len TYPE=integer>Name length</VAR>
  integer :: hash !# <VAR NAME=hash TYPE=integer>Hash</VAR>
  integer :: flag !# <VAR NAME=flag TYPE=integer>Flag</VAR>
  logical :: used !# <VAR NAME=used TYPE=logical>In use flag</VAR>
  integer :: dim1 !# <VAR NAME=dim1 TYPE=integer>First dimension</VAR>
  integer :: dim2 !# <VAR NAME=dim2 TYPE=integer>Second dimension</VAR>
  integer :: allocdim1 !# <VAR NAME=allocdim1 TYPE=integer>First dimension allocation</VAR>
  integer :: allocdim2 !# <VAR NAME=allocdim2 TYPE=integer>Second dimension allocation</VAR>
  integer :: exchange !# <VAR NAME=exchange TYPE=integer>To exchange or not</VAR>
  integer :: ptr_index !# <VAR NAME=ptr_index TYPE=integer>Pointer index at creation</VAR>
  type(r2_t), pointer :: next !# <VAR NAME=next TYPE=r2_t>Next pointer</VAR>
end type r2_t
!# </STRUCTURE>
!=====
```

```
if (acc_is_present(r2%val)) then
  !$acc update device(r2)
  !$acc enter data create(r2%val)
  !$acc parallel loop collapse(2) present(r2%val, r2_tmp) copyin(new_allocdim1, new_allocdim2)
  do j=1, new_allocdim2
    do i=1, new_allocdim1
      r2%val(i, j) = r2_tmp(i, j)
    end do
  end do
  !$acc exit data delete(r2_tmp) finalize
end if
```

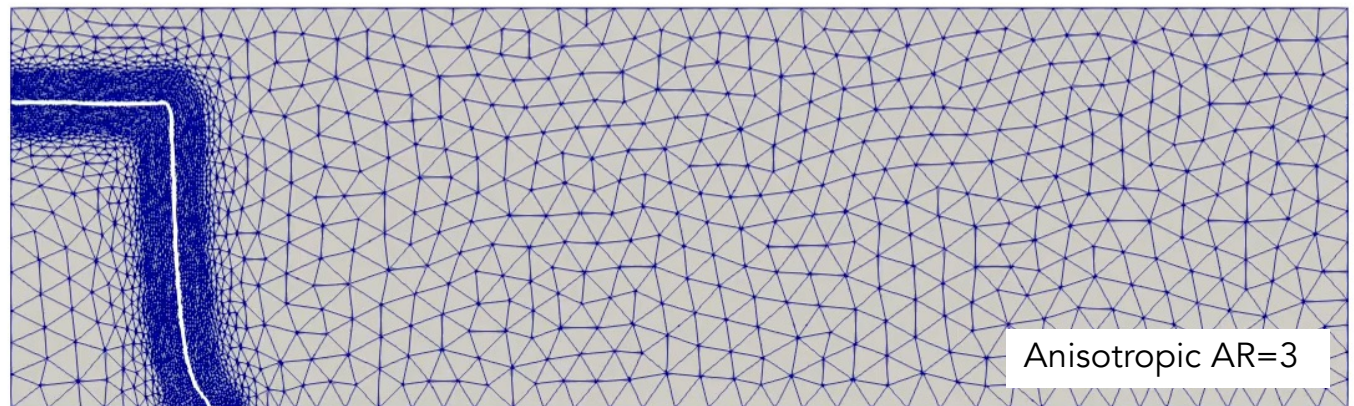
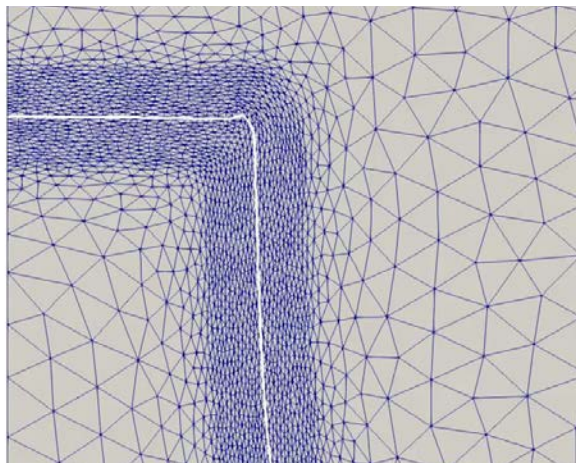
# GPUs & APUs

- Status of OpenACC port in `YALES2_2024.04`
- One solver is ported (SCS), two main solvers on-going (ICS, ECS)
- Supported on
  - NVIDIA, Jean-Zay with gfortran and nvfortran
- Support to come
  - Adatastra AMD MI250: SCS port is done with cce17 but results are still wrong
  - AMD MI300A (APU): CPU port done during ECFD7 Jan. 2024

# Conclusions

# Conclusions

- Data partitioning is the key of efficient unstructured adaptive mesh refinement.
- Many algorithms still need improvement
  - Multi-level contiguous parallel graph coloring
  - Collapse/face swap parallel kernels
- On-going work: anisotropic AMR





# Mesh generation

- Arbitrary STL mesh adaptation

