



CoE Hidalgo2 Urban Building

Workshop NumPEX PC5

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EuroHPC
Joint Undertaking

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CoE Hidalgo2



8 partners from 7 countries:

- **Instytut Chemii Bioorganicznej Polskiej Akademii Nauk (PSNC)** – Poland – Coordination
- **University Of Stuttgart (USTUTT)** – Germany – Technical Coordination
- **ATOS Spain SA (ATOS)** – Spain – Quality Manager
- **Szechenyi Istvan Egyetem (SZE)** – Hungary – Use case owner
- **Meteogrid SL (MTG)** – Spain – Use case owner
- **Universite De Strasbourg (UNISTRA)** – France – Use case owner
- **Erevnitiko Panepistimiako Institutou Systimaton Epikoinonion Kai Ypolgiston-EMP (ICCS)** – Greece – Data analytics and AI support
- **Future Needs Management Consulting LTD (Future Needs)** – Cyprus - Dissemination



Use cases



URBAN AIR PROJECT

Evolution of the air in the urban areas considering pollution, wind, comfort and planning



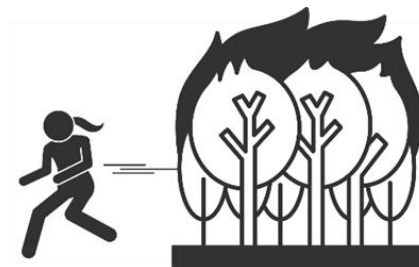
URBAN BUILDINGS

Advanced building models for better integration with architecture. Providing a source term for heat and air pollutants (CO₂ and NO_x) to the urban air pollution model.



RENEWABLE ENERGY SOURCES

Energy production from renewable sources like wind and solar panels. Solution accustomed to urban and rural areas.



WILDFIRES

Simulation of wildfire atmosphere interactions and smoke dispersion in forest and urban areas.

- Urban Air Pollution Pilot
- Urban Building Pilot
 - Overview and Objectives of the Urban Building Pilot
 - Workflow presentation
 - Mesh and Partitioning
 - Modeling and discretization
 - Post-processing and data exchange (coupling) I/O
 - Demo

Urban Air Pollution



1. Importance of urban challenges: 55% of the world's population lives in urban areas now, and 68% by 2050, says UN, see UN DESA at <https://population.un.org/wup/>.

2. Challenge 1: Air quality

- WHO: 6.7 million deaths are attributable each year to exposure to ambient and household air pollution, see <https://www.who.int/data/gho/data/themes/air-pollution>.
- Many cities are polluted (air quality values are above health-critical values)
 - Protests by citizens and new, stricter regulations by policymakers

3. Challenge 2: Wind comfort and safety

- Urban wind can cause discomfort for pedestrians and even critical safety situations in particular near high buildings

4. Challenge 3: Urban planning

- How can urban policymakers mitigate or cease the negative effects of urban challenges?

Most new diesel vehicles exceed emissions limits: German green lobby

REUTERS - Reuters - Most new diesel vehicles exceed the legal limit for nitrogen oxide (NOx) emissions, German environmentalists say, forcing the government to face the consequences of polluting cars.

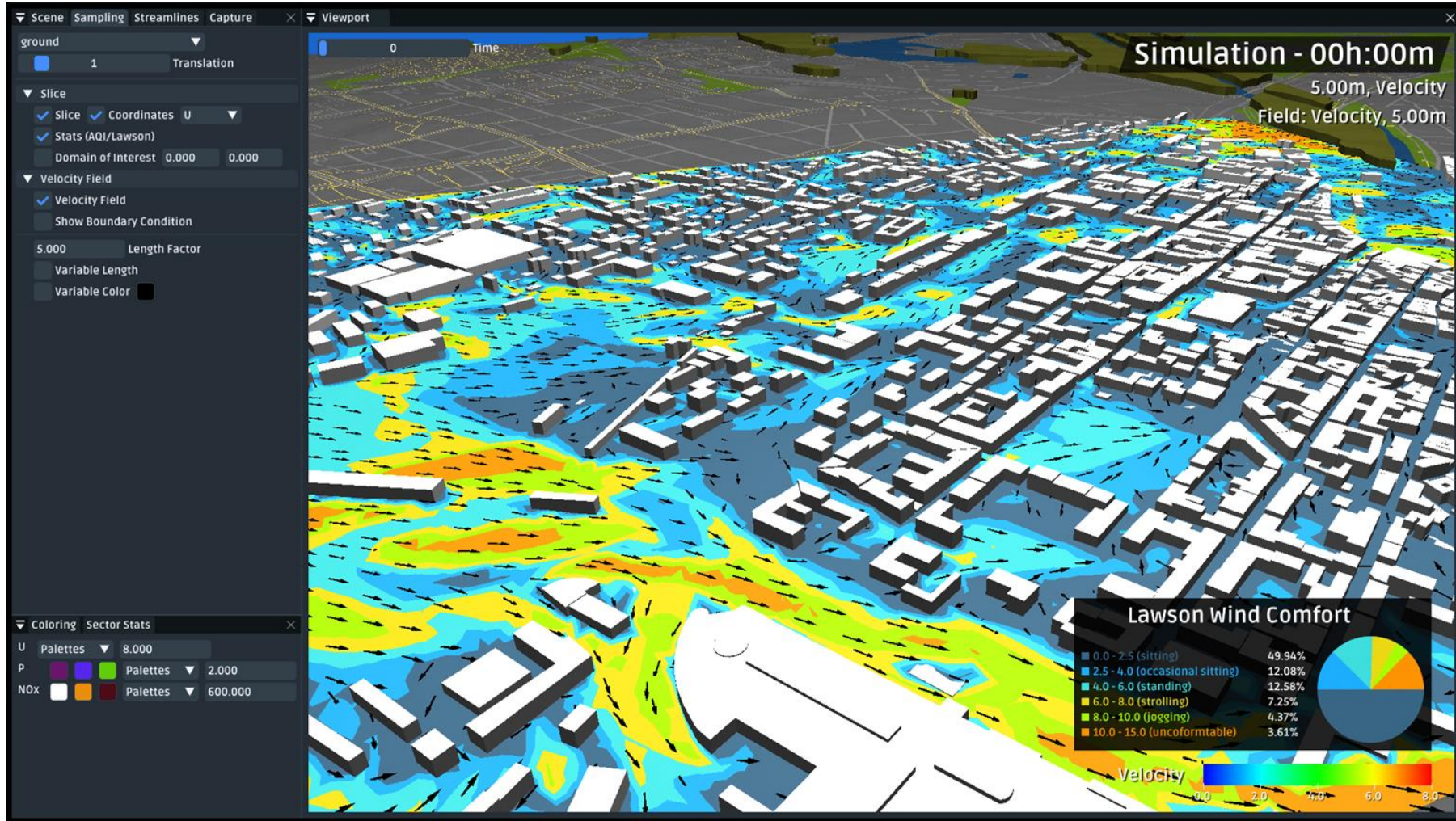


Reuters



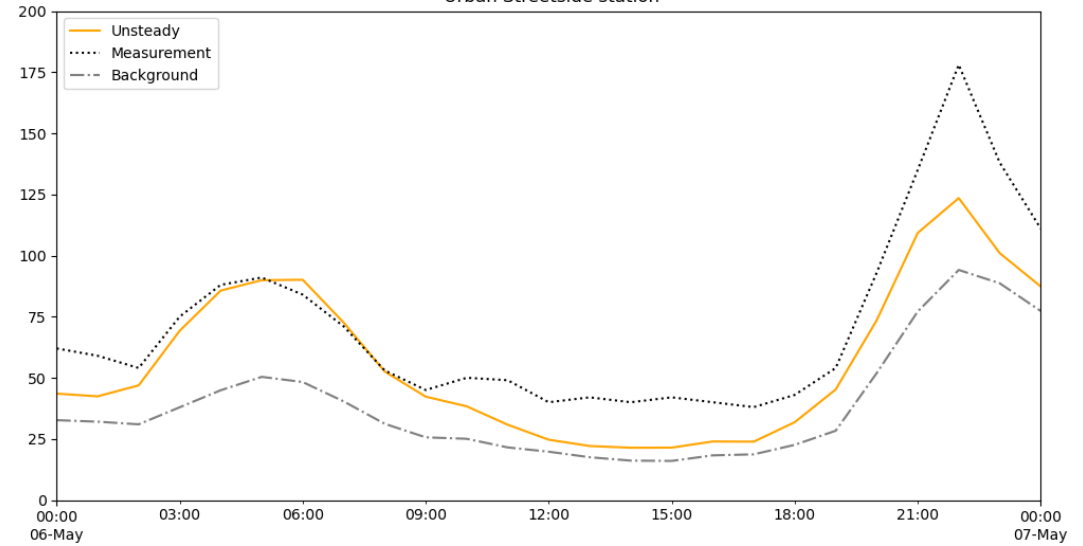
Freepik

Visualization and HPDA postprocessing

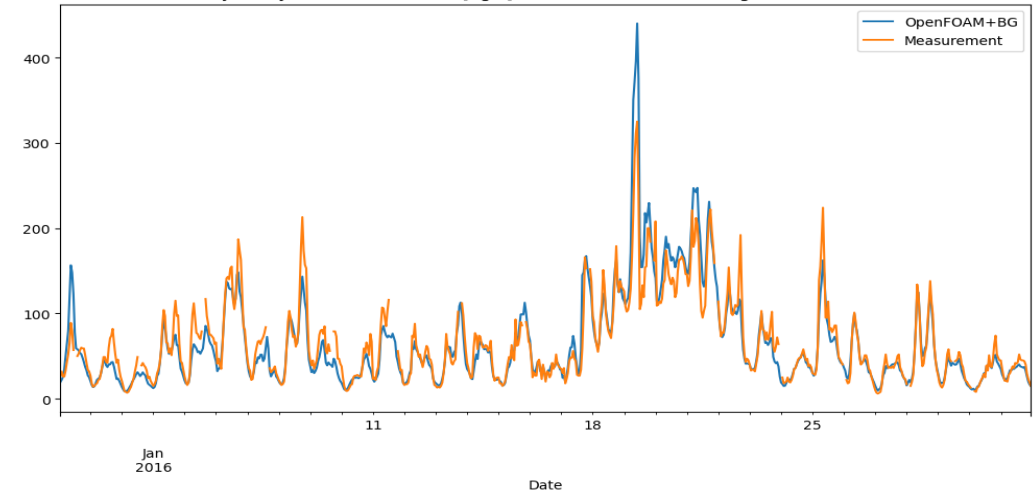




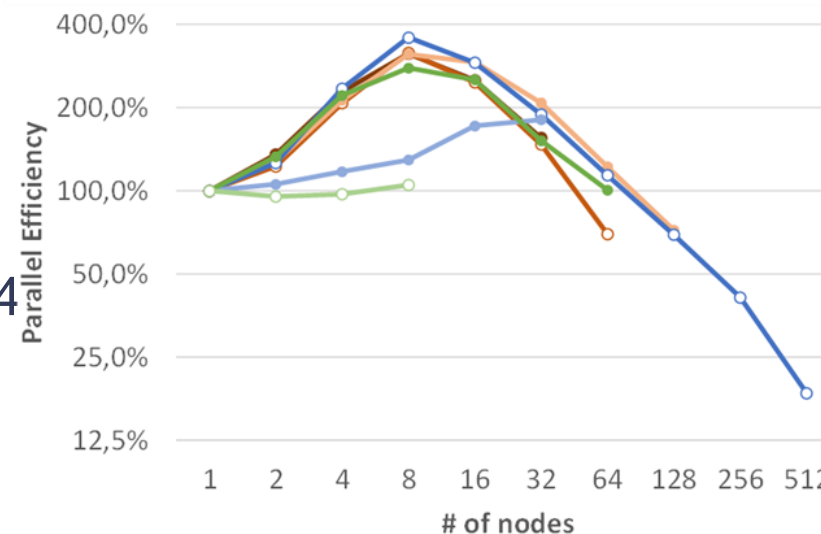
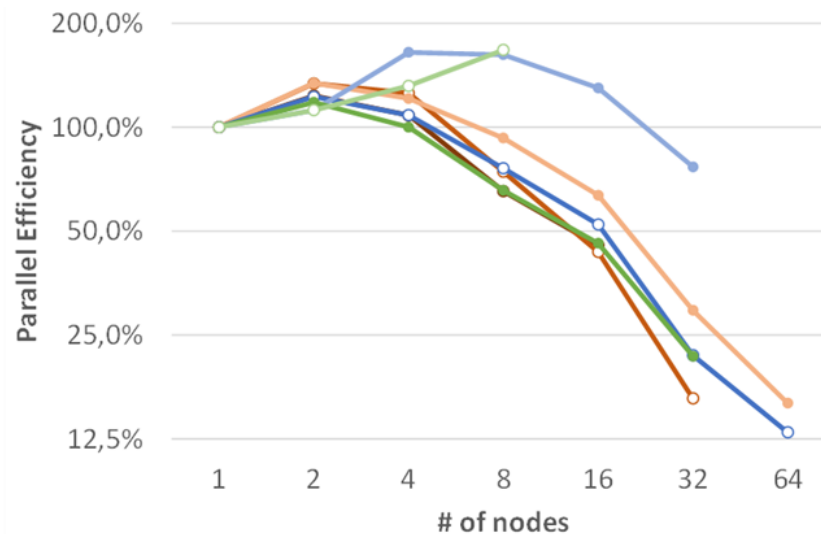
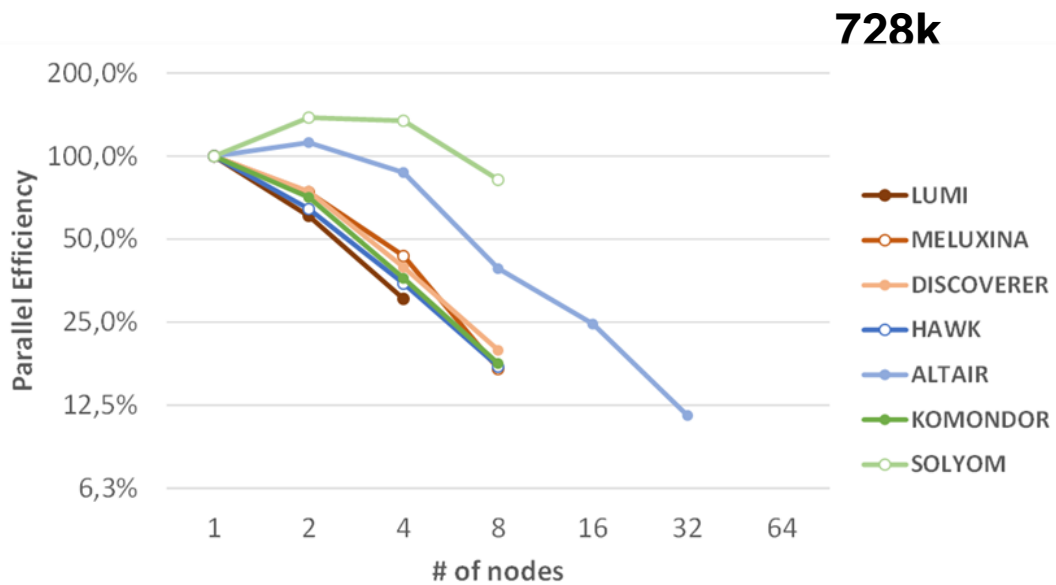
NO2 concentration [ug/s] from 2016-05-06 00:00:00 for X42R802:
Urban Streetside station



January NOx concentration [ug/s] for X42R801: Urban Background station



Benchmarking: Parallel Efficiency with OpenFOAM



- Győr geometry with mesh sizes 728k, 3.4M, 14M
- Testruns on 7 architectures
- Parallel efficiency with regard to 1 node

RedSIM: solver for the compressible Euler and Navier-Stokes equation 2nd order FVM on polyhedral meshes

Code features

- Written in C99-style, compiled as C++, avoids C++ features (STL, templates, exceptions, ...)
- Parallel implementations: MPI+Pthread, multi-GPU (genuinely in CUDA)
- Optimized code, with no dependency, runs easily on each platform we tried (HPC, ...)
- One single algorithm and code for 1D, 2D, 3D
- POD-DEIM model order reduction mode
- Integrated in-house real-time 3D visualizer, interactive (digital twin) feature

Efficiency: Urban Airflow, Gyor. N = 30,291,099		
efficiency	KOMONDOR, 4x NVIDIA A100-SXM4-40GB	VEGA, 4x NVIDIA A100-SXM4-40GB
P = 1	1	-
P = 2	0.9449242544	-
P = 4	0.8752212861	-
Efficiency: Urban Airflow, Gyor. N = 18,342,623		
efficiency	KOMONDOR, 4x NVIDIA A100-SXM4-40GB	VEGA, 4x NVIDIA A100-SXM4-40GB
P = 1	1	1
P = 2	0.9225121646	0.9742910708
P = 4	0.8208693259	0.4716167595
Efficiency: Urban Airflow, Gyor. N = 3,154,126		
efficiency	KOMONDOR, 4x NVIDIA A100-SXM4-40GB	VEGA, 4x NVIDIA A100-SXM4-40GB
P = 1	1	1
P = 2	0.7968193341	0.9222091521
P = 4	0.5919466096	0.4022917729

Wall-Clock Time: Urban Airflow, Gyor. N = 18342623			
wall-clock (s)	KOMONDOR, 4x NVIDIA A100-SXM4-4	VEGA, 4x NVIDIA A100-SXM4-4	SOLYOM, 1x NVIDIA Tesla V100S-PCIE-32GB
P = 1	2781.590725	2783.904732	2127.01869
P = 2	1507.617369	1428.682257	NO DATA
P = 4	847.147846	1475.724026	NO DATA
Wall-Clock Time: Urban Airflow, Gyor. N = 3154126			
wall-clock (s)	KOMONDOR	VEGA	SOLYOM, 1x NVIDIA Tesla V100S-PCIE-32GB
P = 1	432.583269	433.15866	276.966294
P = 2	271.443758	234.848385	NO DATA
P = 4	182.695222	269.181903	NO DATA

Urban Building Overview & Objectives



Building sector in the EU [1]:

- **36%** of GHG emission
- **40%** of final energy consumption

→ Building Energy simulation:

- Accurately assess energy performance of existing buildings
- Identify sources of energy savings (anomalies and areas for improvement)
- Compare and evaluate renovation and/or energy management strategies
- Ensure the optimal management of buildings

Horizon 2050 objectives:

- Double annual energy renovation rates in the next 10 years [2]
- E.g. 700 000 renovation/year in France

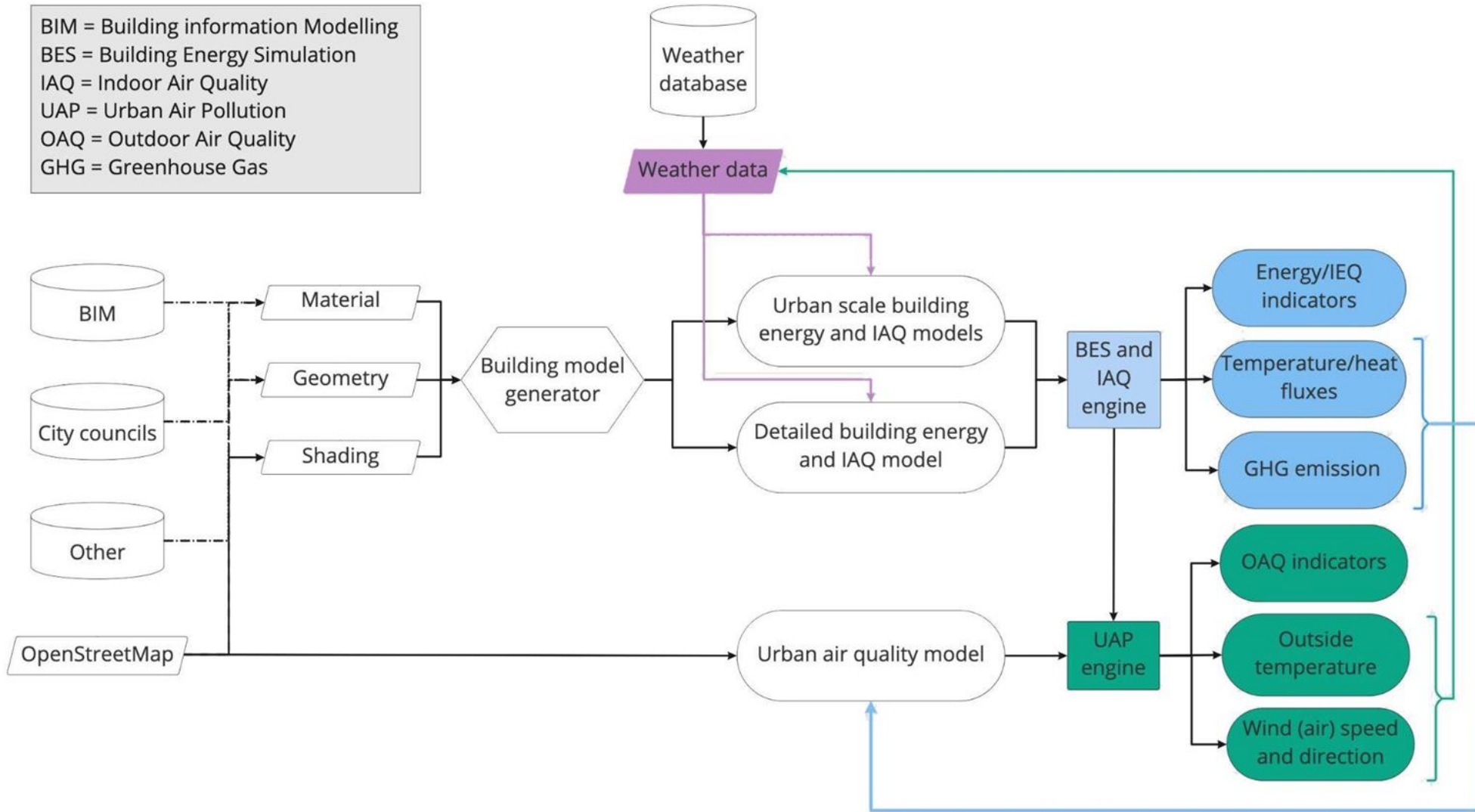
[1]: https://ec.europa.eu/info/news/focus-energy-efficiency-buildings-2020-lut-17_en

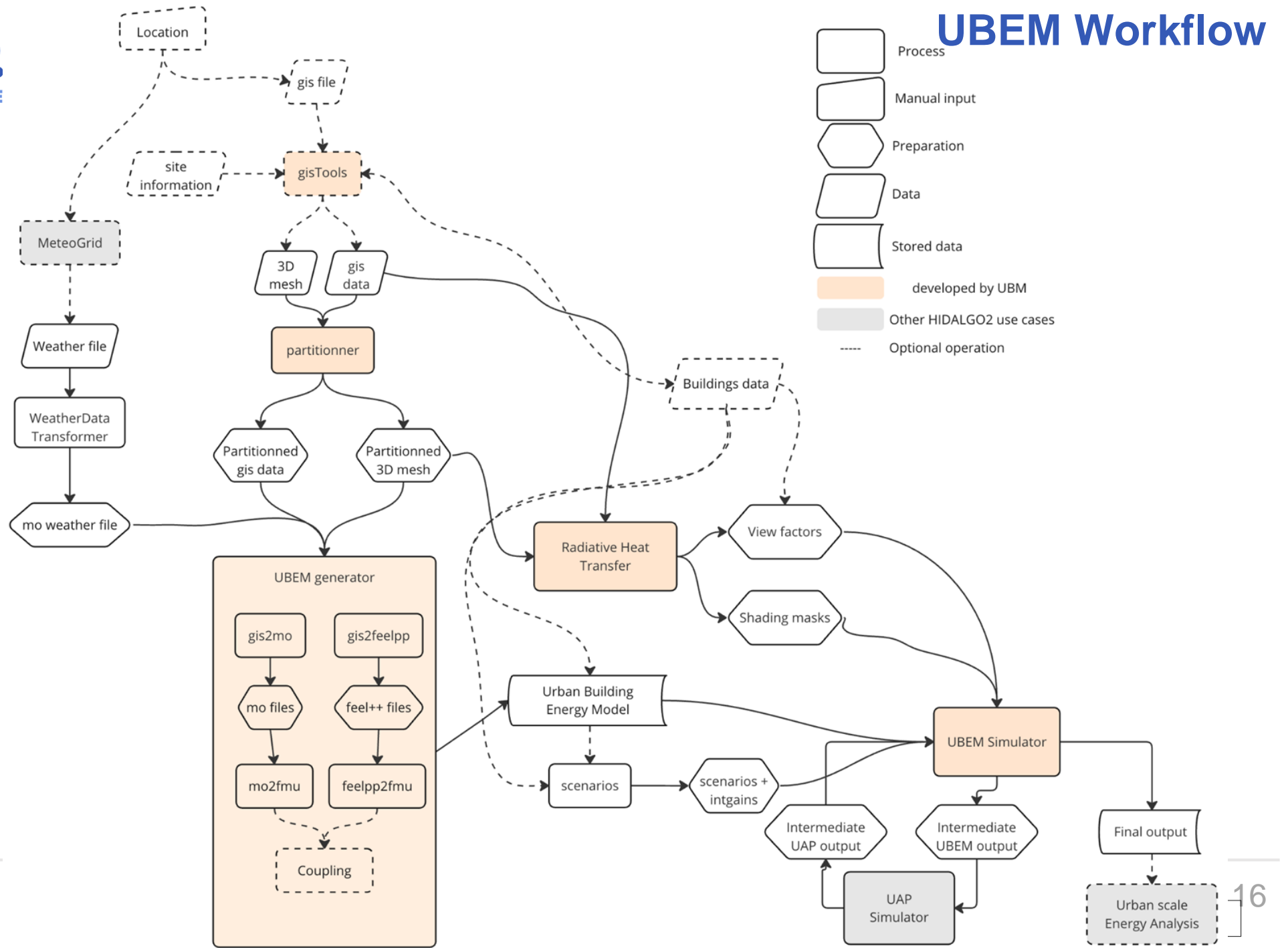
[2]: https://energy.ec.europa.eu/topics/energy-efficiency/energy-efficient-buildings/renovation-wave_en

- Predict energy consumption, thermal comfort and indoor air quality at
 - Building scale
 - Urban scale and beyond
- Integrate the building stock in its environment:
 - Couple with Urban Air Pollution (UAP) model
 - contribution of the building stock (heat and GHG, NO_x) to the outdoor air quality model (UAP)
 - improved boundary conditions of the building model (wind speed, outdoor temperature)
 - Improved radiative heat transfer on buildings' envelope, through a better estimation of solar shading

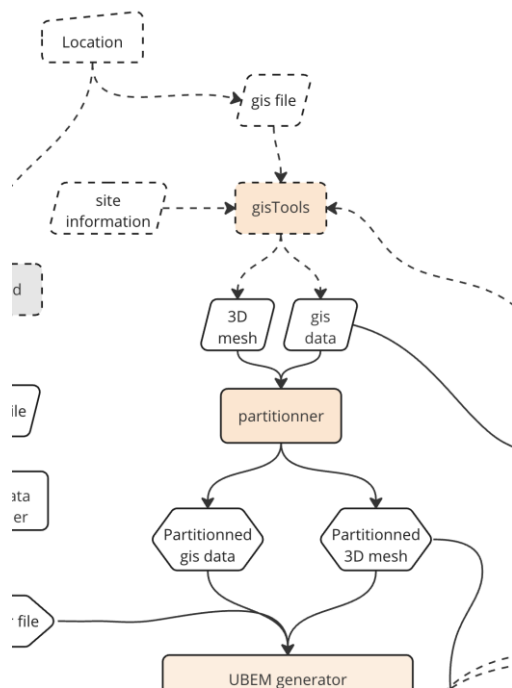
Objectives

BIM = Building information Modelling
 BES = Building Energy Simulation
 IAQ = Indoor Air Quality
 UAP = Urban Air Pollution
 OAQ = Outdoor Air Quality
 GHG = Greenhouse Gas



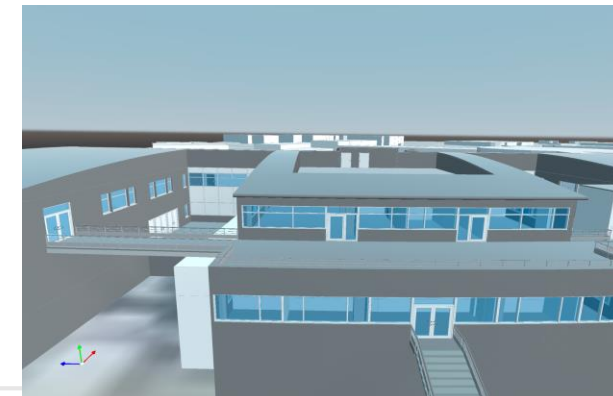
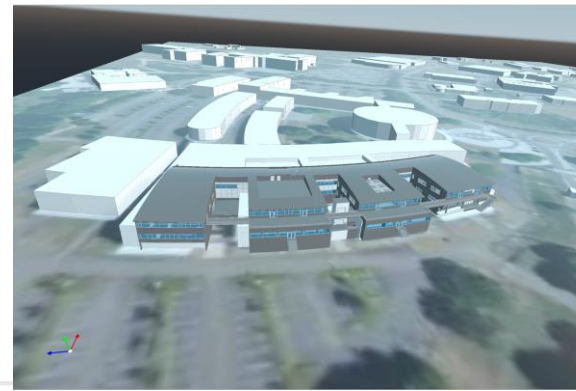
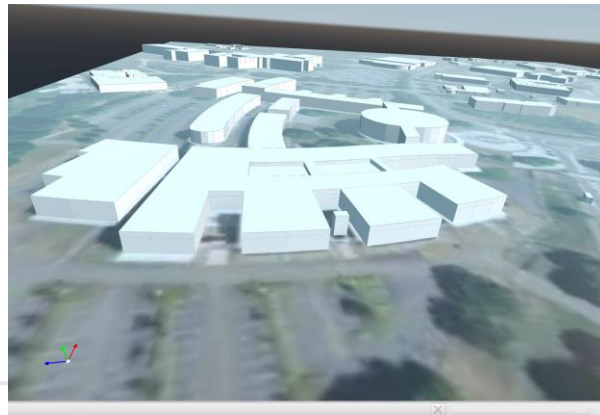
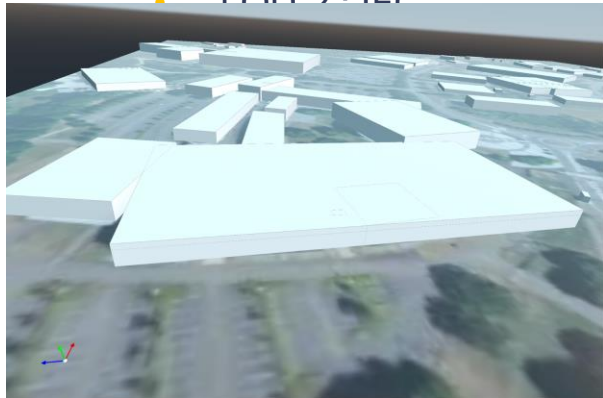
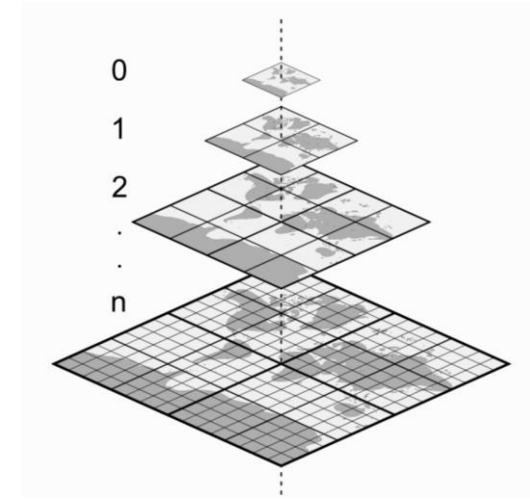
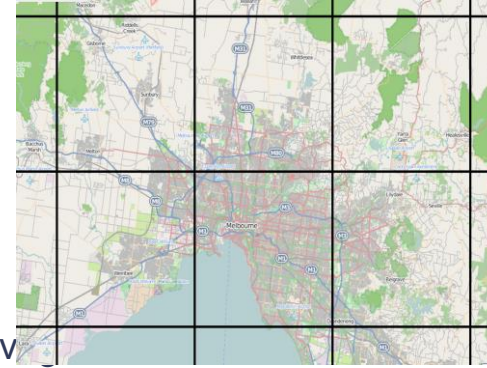


Geometry & Mesh & Partitioning



Geometric reconstruction of urban model

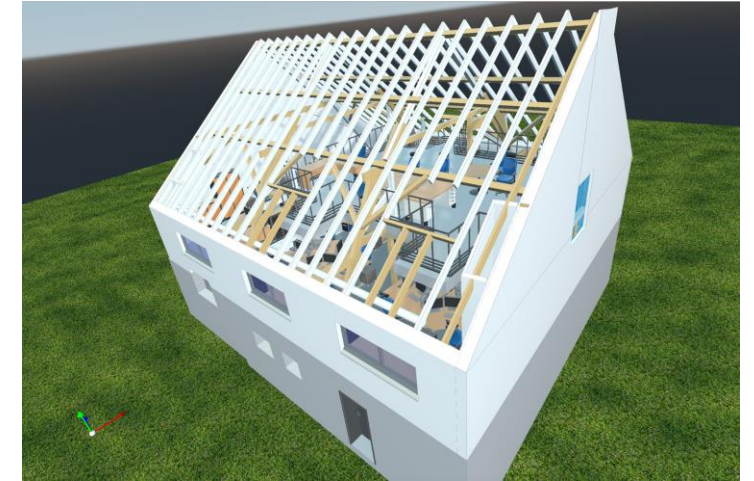
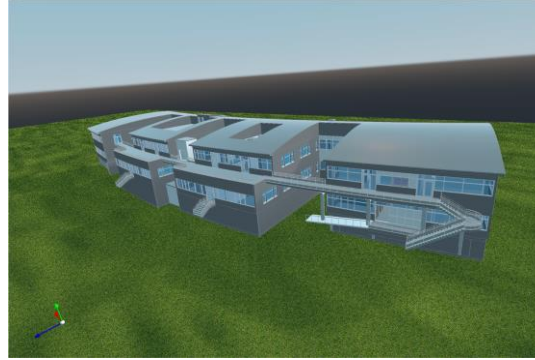
- **Challenge** : Create multi fidelity representation of buildings, terrain, vegetation, ...
- Tiled web map approach
 - Distributed data, adapt Level Of Definition (LOD)
 - Constraint : require gluing the tiles
- Buildings LOD
 - LOD-0 : Oriented bounding box
 - LOD-1 : Polygonal extrusion (+roof)
 - LOD-2 : IFC
- Terrain
 - Elevation from raster images
 - Include roads, parks, railways, rivers, ...



Building meshes (LOD-0, LOD-1)

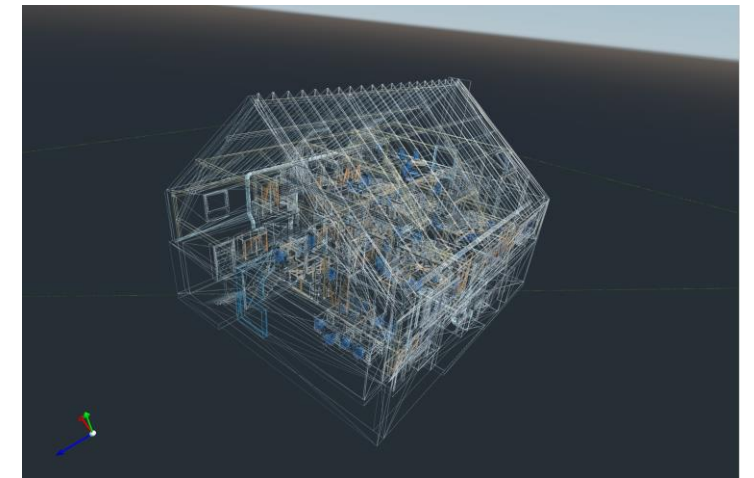
- Metadata fetched from the web (OpenStreetMap)
 - Multi polygons with holes
- Building LOD-0
 - Compute 2D oriented bounding box from building footprint
 - Extrusion applied with max height
- Building LOD-1
 - Composed of one or several parts defined by a polygonal extrusion
 - Apply union of all parts : generate one or several volumes for a building
- District/city
 - Collection of buildings
 - Apply union operations with building touching, or even intersecting
 - Optimization : building grouping from bounding box





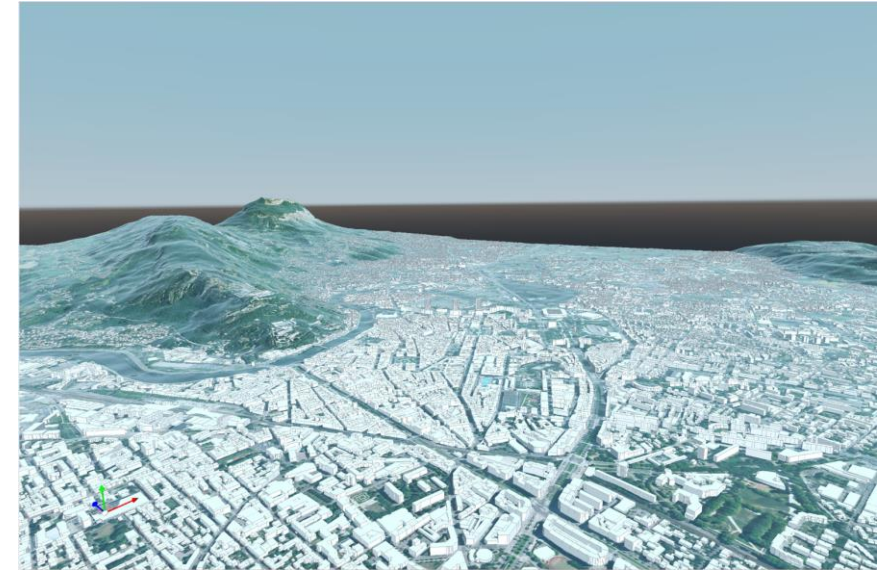
Building meshes (LOD-2)

- Geometry from Building Information Modeling (BIM)
 - IFC format
 - Surface model
 - Solid model : Swept, B-REP, CSG
- A geometry for each entity of building
 - Often non-conforming, not watertight
 - Allow to filter by entity type : structural, furniture, electric, plumbing, ...
 - Mesh generator : Open-Cascade, Carve (IFC++), ...
- **Challenge**
 - Conformal surface mesh
 - Volume mesh : watertight
 - Mesh Adaptation



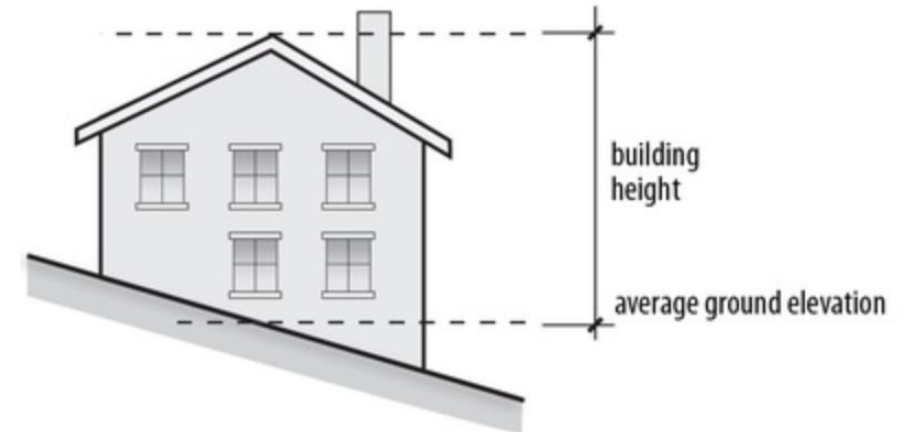
Terrain

1. Start by creating a uniform mesh (based on the raster image size)
2. Evaluate the elevation on each node
3. Compute isolines and mesh adaptation (reduce the number of element)
4. Glue each tile



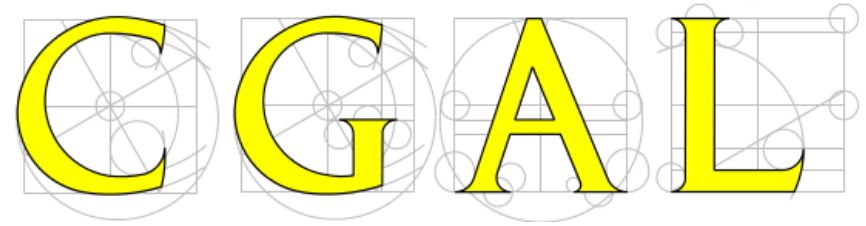
Terrain + Buildings

- Conforming and watertight mesh
- Building (or any object) on a slope requires adapting the height
- Algorithm
 - a. Compute difference of planar terrain and building footprint.
 - b. Apply terrain elevation.
 - c. Adapt building height.
 - d. Insert building in the hole and repair mesh intersection.



Current strategy [MT]

1. From location, determine tiles used [Sequential]
2. Download GIS data (buildings, elevation) [Parallel MT]
3. Polygons repair [Parallel MT]
4. Terrain mesh generation [Parallel MT]
5. Union of building at tile junctions [Sequential]
6. Building mesh generation [Parallel MT]



Next Steps towards full parallel mesh generation [MPI+MT]

- Objectives : large city scale and beyond
- Use distributed computing (MPI)
- Create partitioning of tiles with overlapping (ensure fetch full building description)
- Create parallel mesh
 - Use MT strategy in each process
 - Overlapping zone allows creating full buildings without MPI Comm

- Input
 - Mesh of urban model (naturally partitioned thanks to tiled web map)
 - Number of partitions requested
 - Load balancing : weight parameter assigned to each building (depends on modeling complexity and solver)
- Output
 - Partitioned mesh used as input of urban building energy modeling

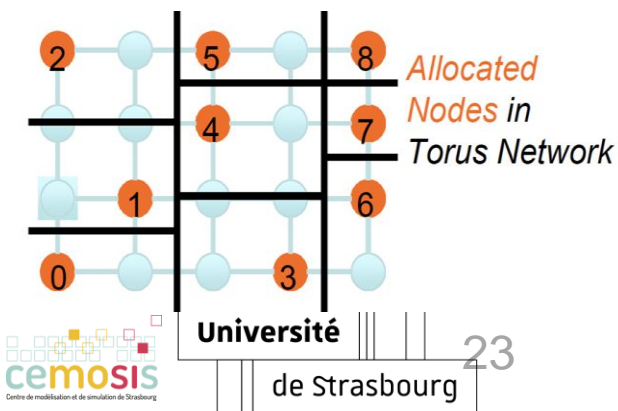
- Locality-aware partitioning
 - Building grouping
 - Interaction with the building's surroundings (solar shading, vegetation and river, ...)
- Partitioning strategies :
 - Graph-based
 - Mesh connectivity
 - Toolkits : METIS, ParMETIS, SCOTCH, PT-SCOTCH, KaHyPar, Zoltan2, ...
 - Geometric :
 - Uses coordinates of mesh entities
 - Toolkits : Zoltan2...
- Architecture-Aware Task Placement
 - Given a (possibly non-contiguous) allocation of nodes in a parallel computer, reduce application communication costs by assigning interdependent MPI tasks to “nearby” cores within the allocation
 - Important in extreme-scale systems

Zoltan2

- Parallel partitioning : MPI+X (multicore,GPU)
- Geometric partitioning
 - MPI+OpenMP
 - Fast and scalable
- Graph partitioning via interfaces to PT-SCOTCH, ParMETIS,
- Architecture-Aware Task Placement

Tasks

2	5	8
1	4	7
0	3	6



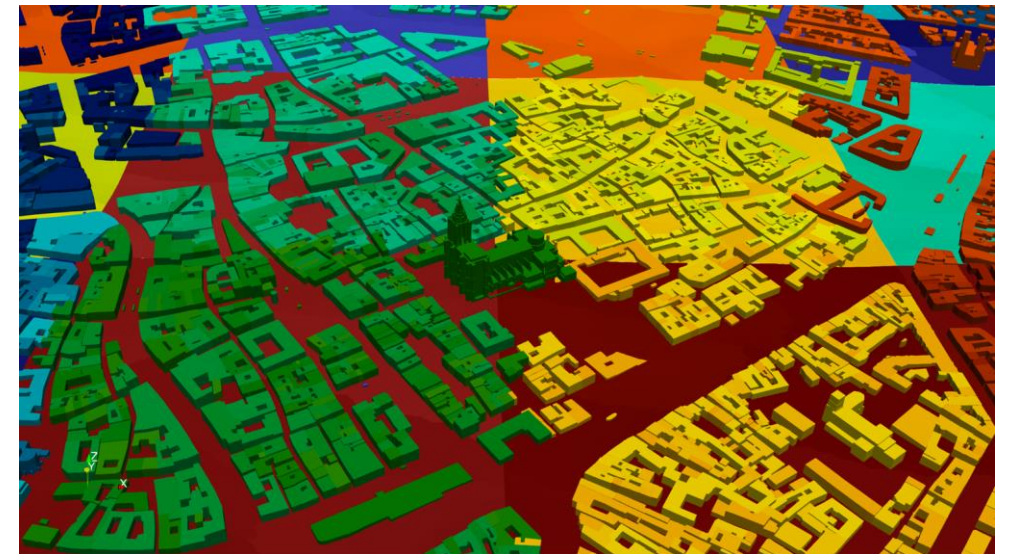
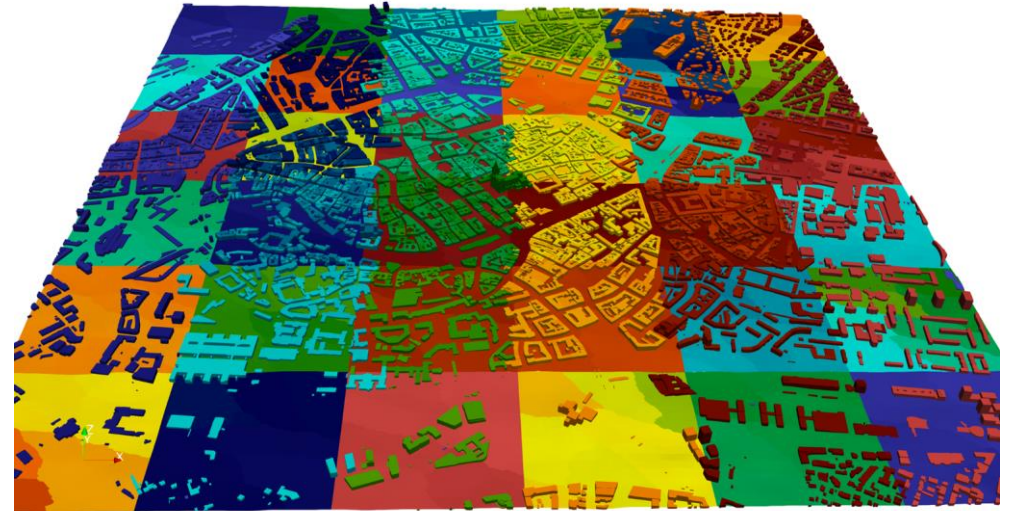
Test case 0 : buildings mesh

- Context
 - Building model has no interaction with environment
 - Only buildings mesh, no terrain, no vegetation ...
- Partitioning methods
 - Use only the building listing (no spatial relation) and weights
 - Geometric partitioning
 - Weighted graph partitioning from a triangulation of building barycenter



Test case 1 : fully non-conforming mesh

- Context
 - Building model interact with environment and surrounding buildings
 - Building meshes are conforming and watertight
 - Terrain, vegetation mesh are non-conforming
- Partitioning methods
 - Geometric partitioning
 - Weighted graph partitioning
 - Buildings : Triangulation of building barycenter + Weighted + Building grouping
 - Terrain (and other structures) are partitioned independently and without constraint



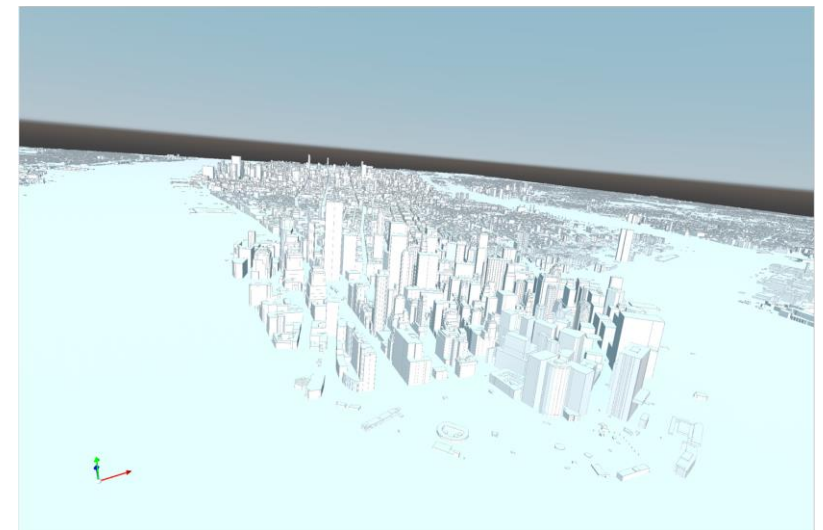
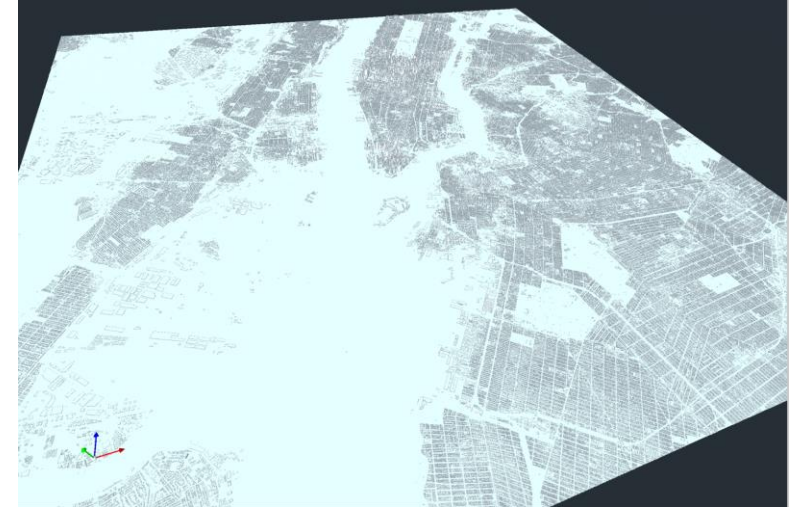
Test case 2 : full conforming mesh partitioning

- Context
 - Building model interact with the environment and surrounding buildings
 - Coupling pilots of Hidalgo 2 : UAP
- Weighted graph partitioning
 - Apply on full mesh
 - Start with buildings, then environment constraint with building partitioning
- Minimize communication cost compared to test case 1

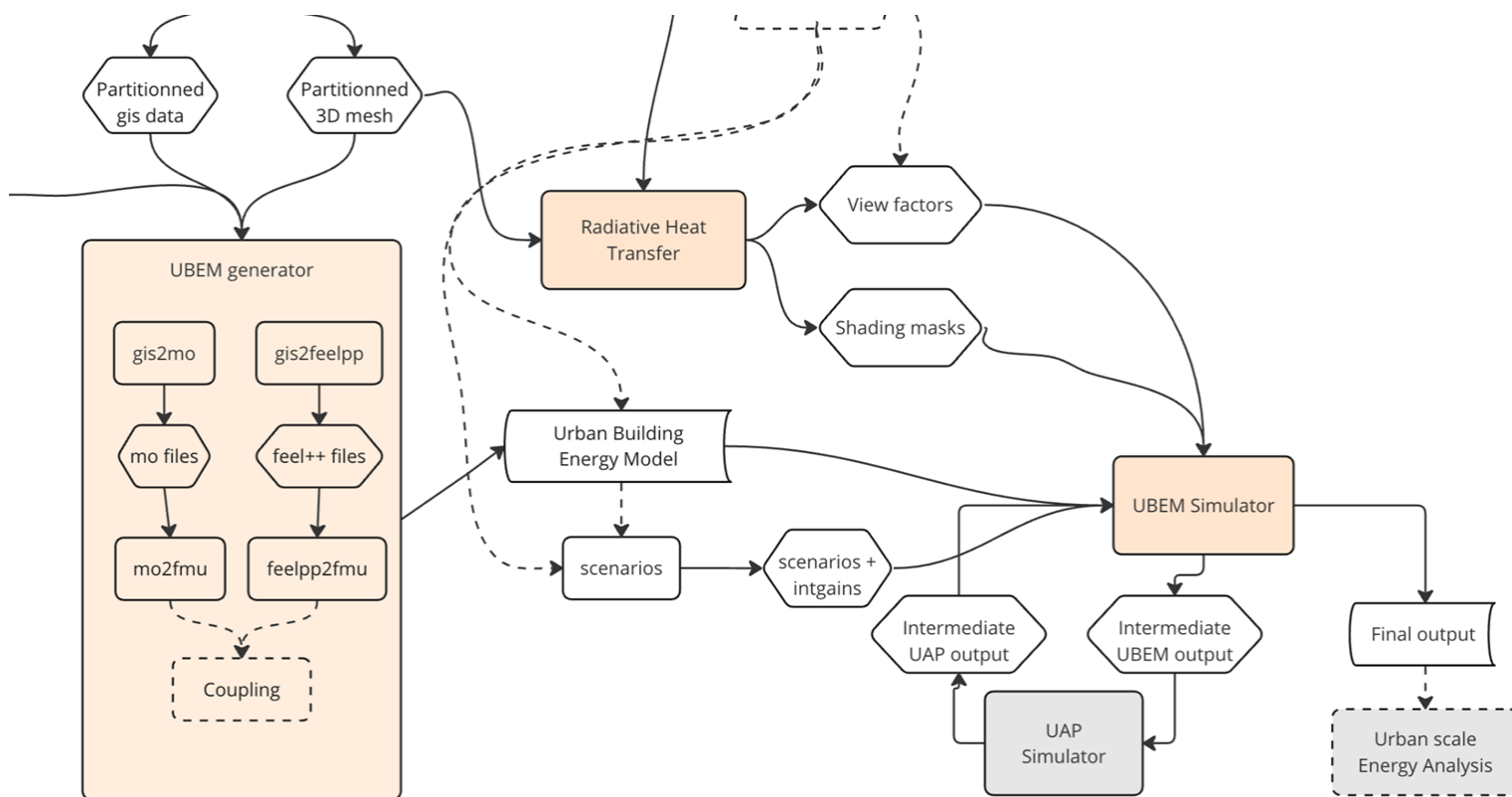
Test case 3 : toward extreme number of partitions

- Multigrid approach
- Define coarse mesh (compute at GIS analysis phase)
 - District level with smart cutting (convex hull, ...?)
 - Mesh as macro partitioning : each part (or grouping part) will define a subset of micro partitions

Apply previous methodology in each macro partition



Modeling & discretization



```

...
auto Vh = Pch<4>( mesh, markedelements(mesh, expr("<...>")) );
auto u = Vh->element(), v = Vh->element( g, "g" );
auto l = form1( _test = Vh );
l = integrate( _range = elements( support( Vh ) ),
              _expr = f * id( v ) );

l += integrate( _range = markedfaces( support( Vh ), "Robin" ), _expr = -r_2 * id( v ) );
l += integrate( _range = markedfaces( support( Vh ), "Neumann" ), _expr = -un * id( v ) );

auto a = form2( _trial = Vh, _test = Vh );
a = integrate( _range = elements( support( Vh ) ),
              _expr = inner( k * gradt( u ), grad( v ) ) );
a += integrate( _range = markedfaces( support( Vh ), "Robin" ), _expr = r_1*idt(u)*id(v));
a += on( _range = markedfaces( support(Vh), "Dirichlet" ), _rhs=l, _element=u, _expr = g );
a.solve( _rhs = l, _solution = u );

```

Feel++

- Framework to solve problems based on ODE and PDE
- C++17 (C++20) with a Python layer using Pybind11
- Seamless parallelism with default communicator
- DevOps: CI/CD (docker/apptainer + ubuntu/debian packaging soon spack or guix-hpc)
- Tests: Hundreds of tests run in sequential and parallel C++ and Python
- Usage: Research, R&D, Teaching, Cloud Services



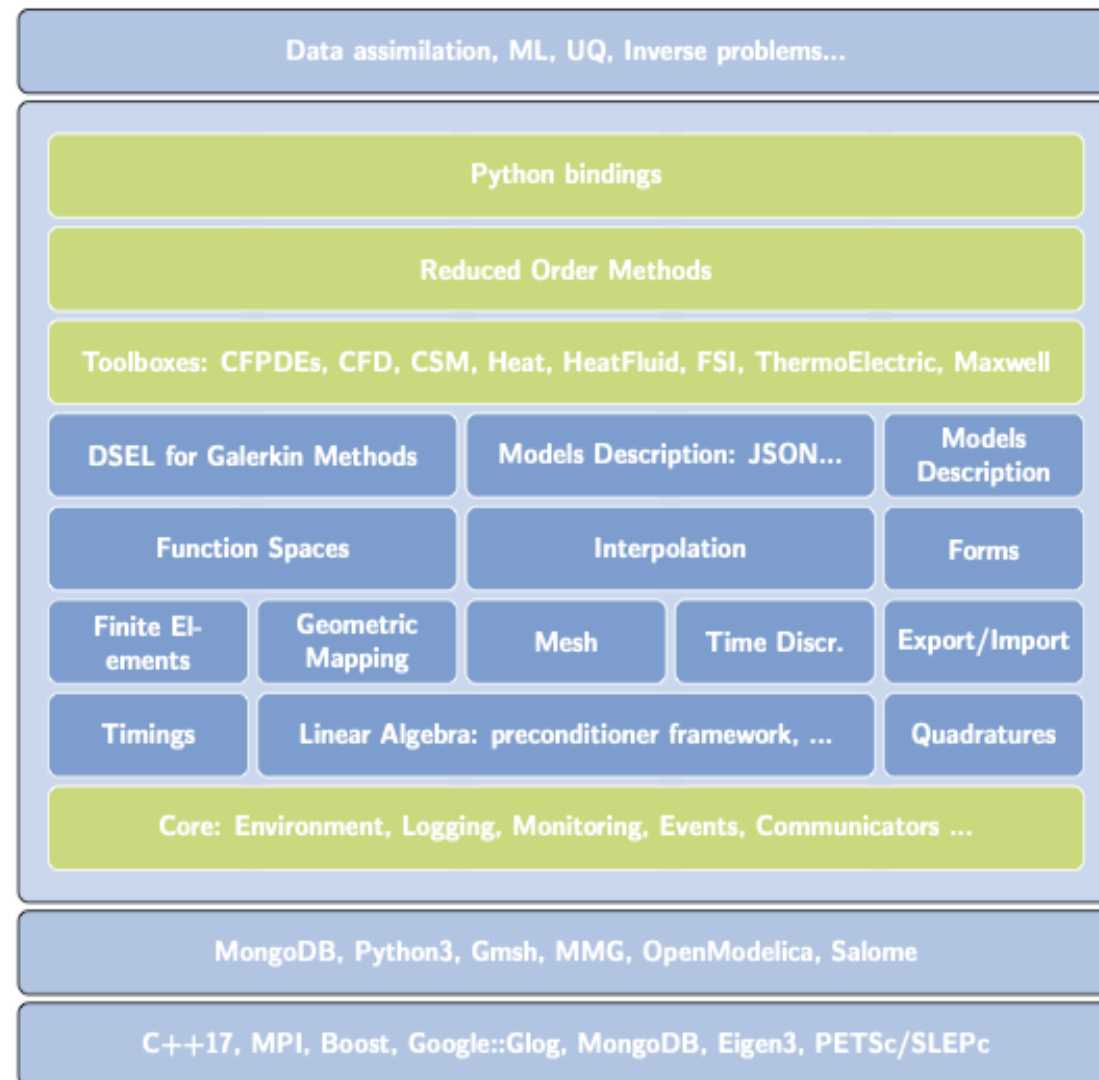
Feel++ : some features

- A large range of numerical methods to solve PDEs: cG, dG, hdG, rb/moi
- 0D+t, 1D(+t), 2D(+t), 3D(+t)
- DSEL for Galerkin methods in C++
- De Rham complex : arbitrary order
- Cross the bridge between symbolic and numeric computing
- Automatic differentiation
- Seamless interpolation
- WIP : Use Specx Task-based runtime system > [Github](#)

```

auto u = Xh->element();
// expression handling
auto e3 = expr( "2*x*u*v:x:u:v" );
auto e3v = expr( e3, symbolExpr( "u", dxv( u ) ), symbolExpr( "v", Nx() ) );
// remeshing in seq and //
auto rm = remesh(_mesh=mesh,_params=<remeshing specs in json>);
// Fast marching : compute distance to range
auto distToBoundary = distanceToRange( _space=Vh, _range=boundaryfaces( mesh ) );
auto distToBoundaryNarrowBand =
    distanceToRange( _space=Vh, _range=boundaryfaces( mesh ),
                    _max_distance=3.*mesh->hAverage() );

```

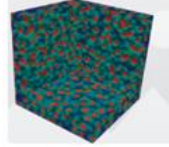


docs.feelpp.org/toolboxes/latest



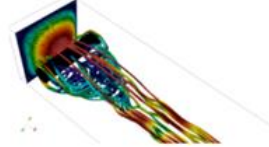
1. Core Manuals

The Toolbox Core Manuals describe (i) what is a toolbox (ii) how to setup simulation models thanks to JSON files and (iii) configure command line options of the toolboxes



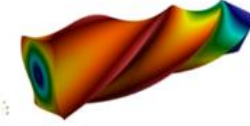
Coefficient Form PDEs

A coefficient form PDE toolbox to solve N coupled nonlinear PDEs



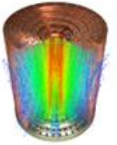
Computational Fluid Mechanics

The computation fluid mechanics solves from low to high Reynolds number flows and includes some turbulence models.



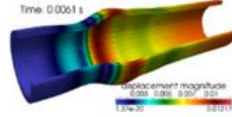
Computational Solid Mechanics

A toolbox to solve non-linear elasticity problems that supports (i) Large deformations, (ii) large displacements; (iv) Compressible, nearly incompressible materials and (v) Multi-material



Electric

A Toolbox that solves Gauss's Law equation and compute the electric potential and field of a given charge distribution.



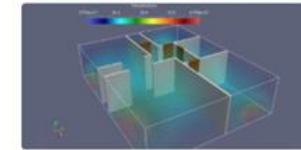
Fluid Structure Interaction

A toolbox for solving fluid-structure interaction problems using ALE formulation and staggered schemes such as Dirichlet-Neumann, Generalized Robin-Neumann, and Robin-Robin.



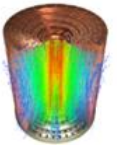
Heat and Fluid

A toolbox that solves the heat and fluid equations including convection, conduction effects. it is mostly used for aerothermal problems.



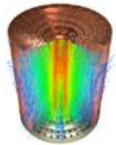
Heat Transfer

A toolbox to solve heat transfer problems including conduction, convection and black body radiation including non-linear problems and temperature dependent properties.



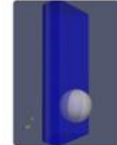
Hybridized Discontinuous Galerkin Toolbox

Hybridized Discontinuous Galerkin Toolbox case studies, supporting elliptic and parabolic problems in 2D and 3D including advection, diffusion and reaction, elasticity, Stokes and coupled problems.



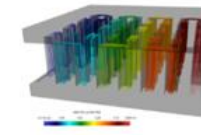
Maxwell

A toolbox for the simulation of electromagnetic fields in 3D including static, low frequency, and high frequency applications and non-linear materials.



Multifluid Flow Toolbox

A toolbox to solve multfluid flow problems using the level set method



Thermo-Electric

A toolbox to solve the heat equation coupled to the electric currents equation including temperature-dependent material properties.

View factors

Describe the fraction of radiation leaving a surface and hitting a second surface

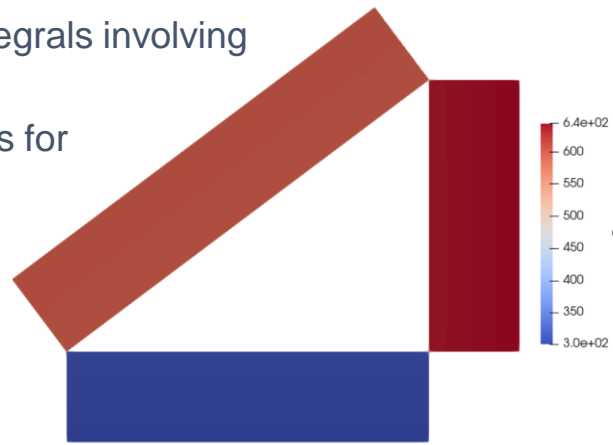
- Purely geometric quantities

Numerical method: Monte Carlo and ray tracing

- Geometries with obstructions
- Only gray surfaces for the moment, but specular could be considered

Challenges

- Efficient computation of integrals involving view factors
- Computation of view factors for specular surfaces (several bounces)
- Efficient storage



Use Feel++ identified by PC1- Exa-MA

Solar masks

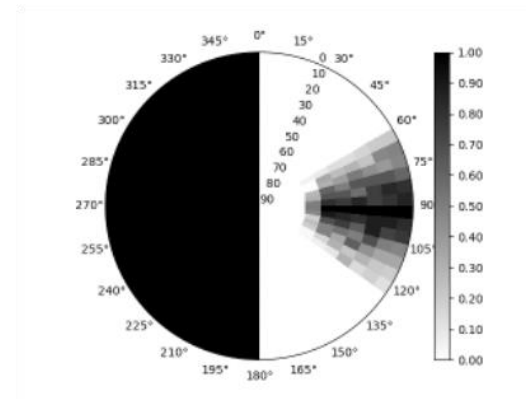
Describe the percentage of blocked solar radiation for each building surface (walls, roofs) and ray direction

- Caused by surrounding buildings, vegetation, urban furniture
- Can be computed per surface or per building

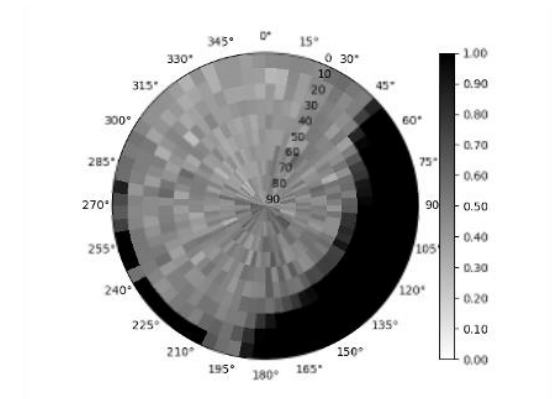
Numerical method: Monte Carlo and ray tracing

Challenges

- Computation on large-scale mesh and storage

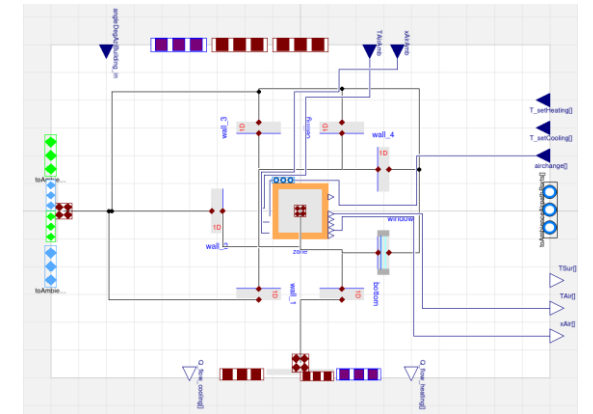
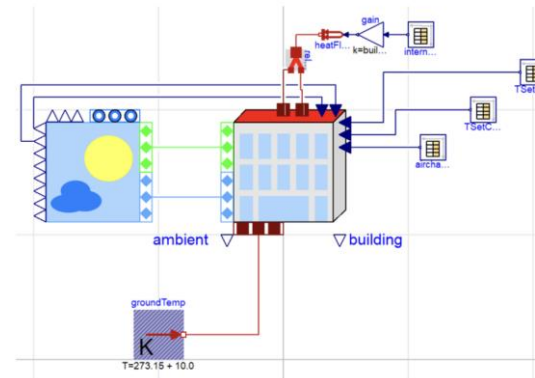
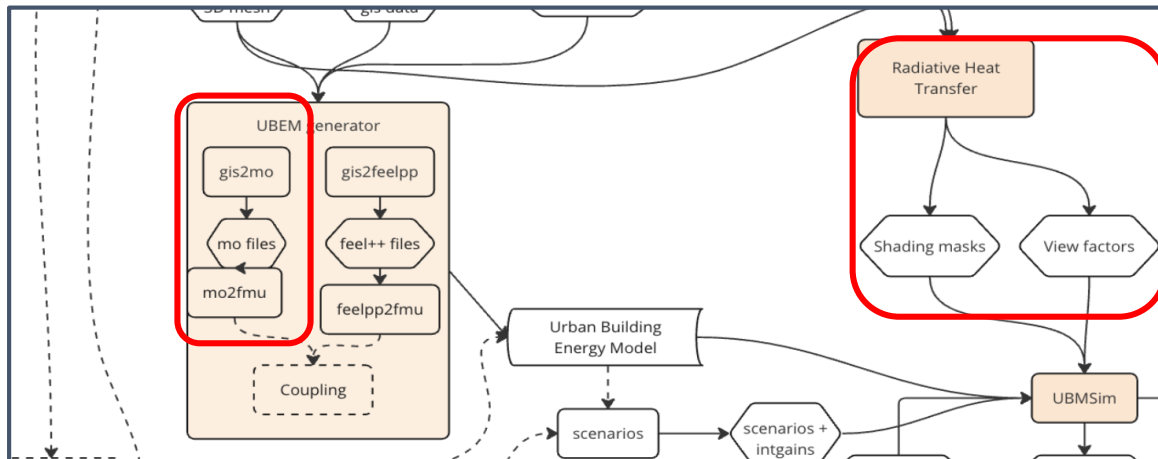
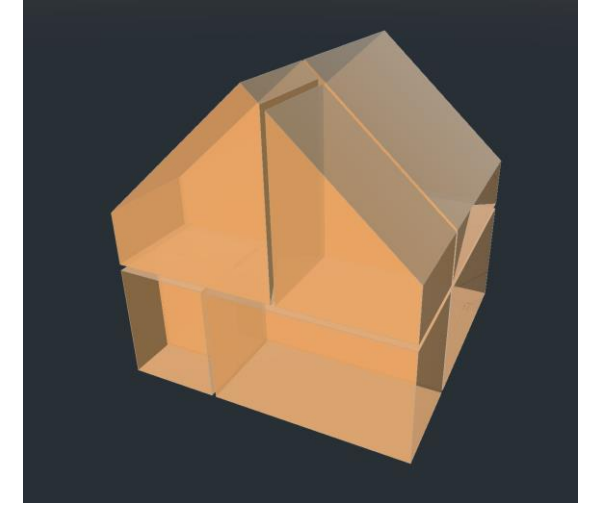
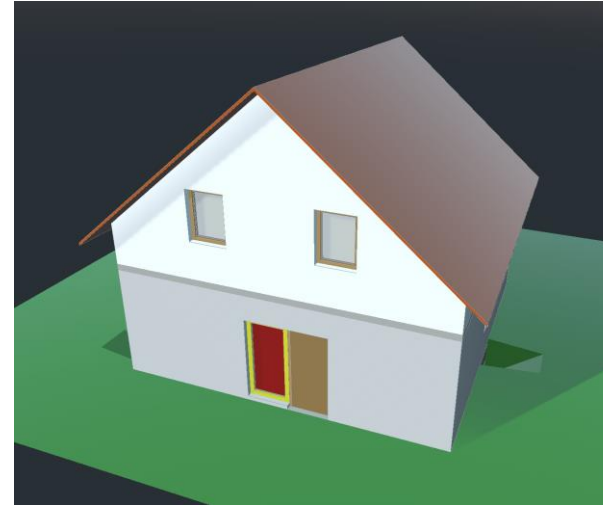


East-facing wall shadowed by a tall building in front of it



Shading mask for a whole building

- Multizone model for building energy simulations
- Use Modelica language with extensive support for building energy modeling
- Multifidelity models: LOD-0, LOD-1
- Generate FMU (Mo transformed into C/C++)
- Sequential (some MT support)



Predict energy consumption, thermal comfort and internal air quality

- Detailed description of internal air temperature
- Fast computations and scenario evaluation

Models

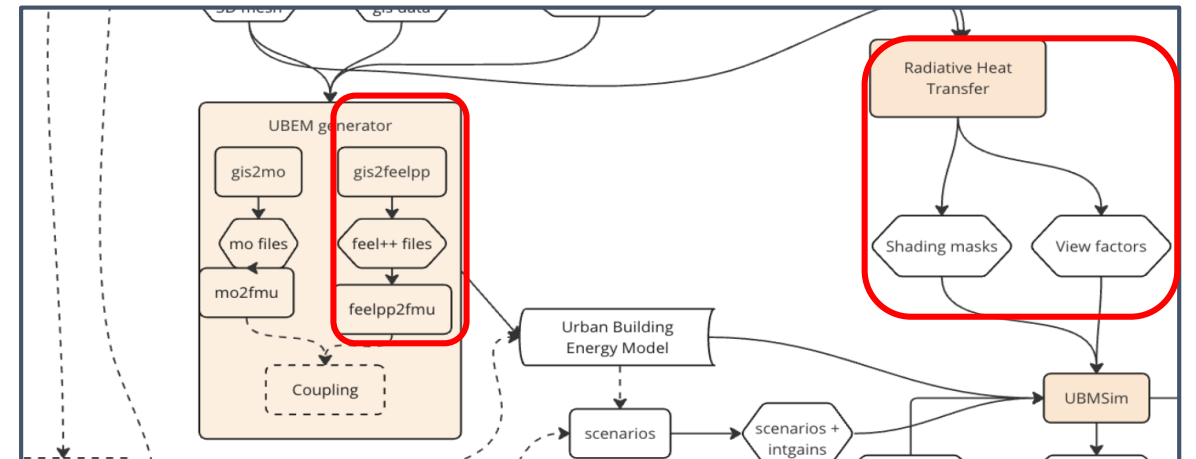
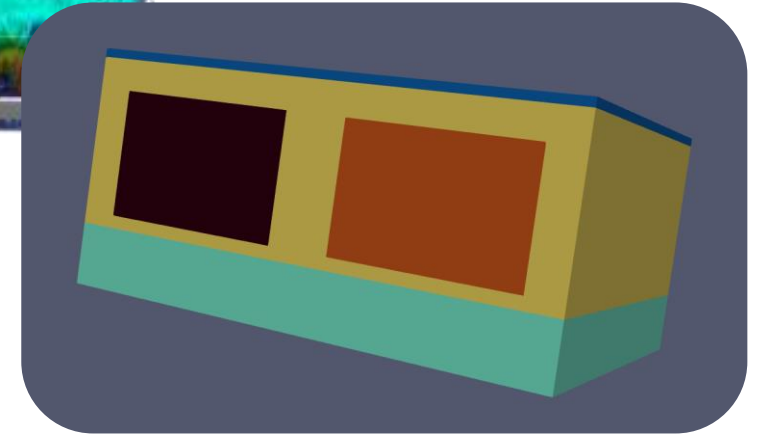
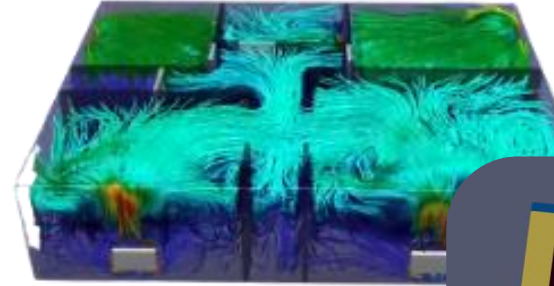
- Steady state building model
- Unsteady model accounting for multi-layer walls and window openings
- Solar radiation and shading from the surrounding environment

Numerical methods

- Finite element and reduced basis methods
- Data assimilation for parameter estimation
- Parallel-in-time algorithms
- Model order reduction using eg RB

Challenges:

- Large number of parameters
- 3D-0D couplings



Use Feel++ identified by PC1- Exa-MA

Hybrid computing

- Strong link to Mesh Partitioning/Load balancing (see mesh section)
- Finite element method: use our DSEL to hide "details" (-> Mfem, Kokkos, Eigen, ...)
- Reduced basis model (offline see above, online opencl implementation, large scale DB storage)
- Solar mask and view factors computing
 - Current CPU implementation very fast. testbed for specx (task-based runtime execution)
 - Well suited for GPU computing
 - Should we store the masks and view factors or recompute them in situ? (probably both options are relevant)
- Multizone models: currently a strong bottleneck as we do not control the generated code

Post Processing I/O & Data Exchange



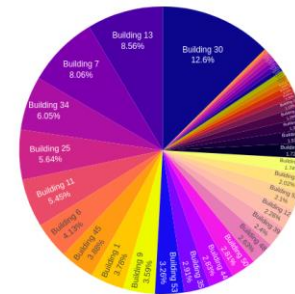
Save buildings simulation outputs

- Outputs : Temperature, Humidity, Energy, CO2, NOx, ...
- Frequency : at each time step (or over time points)
- Measures location :
 - On each building (global values)
 - On each building face
 - On each node/element of the (surface) mesh

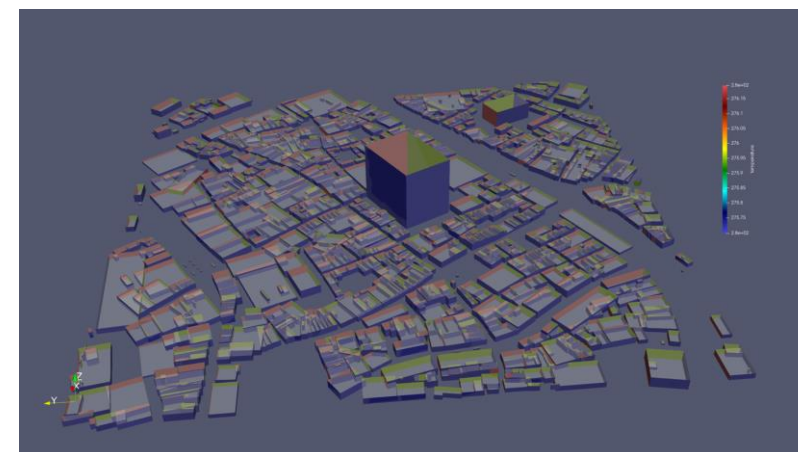
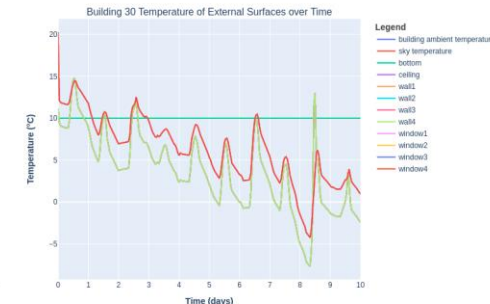
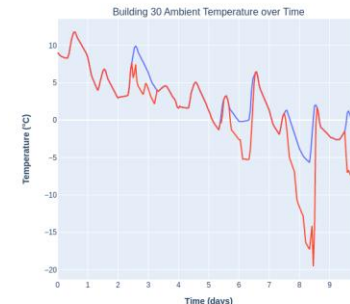
Use cases

- Statistical analysis
 - Reporting generation, plot chart : line, bar, pie, ...
 - Compute indicator : comfort, energy, ...
- 3D visualization : ParaView, Ktirio, ...
- Data exchange (coupling with another application)
- Restart simulation

Energy Consumption of the District (Pie Chart)



Study of Building 30 Temperatures

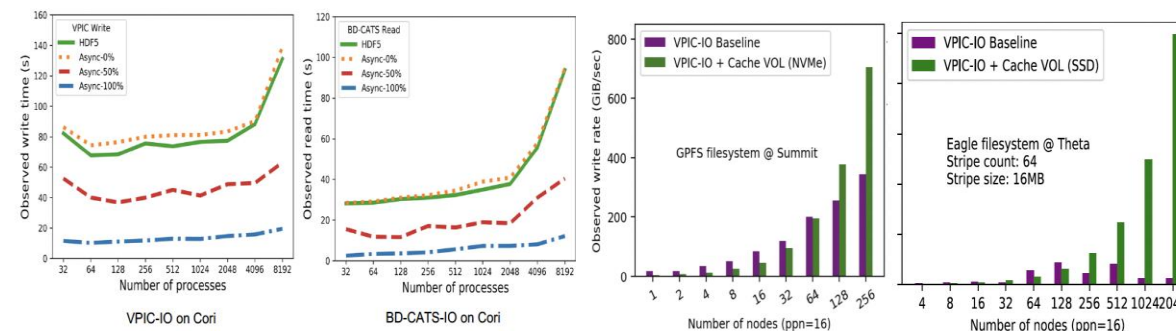
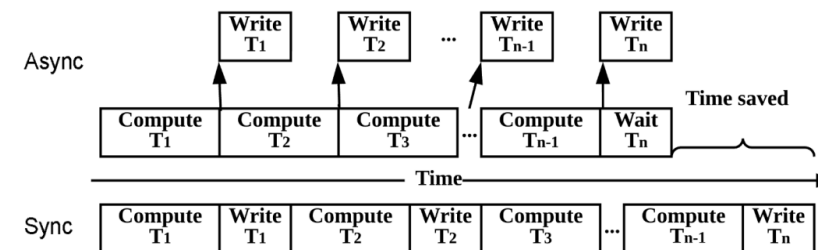
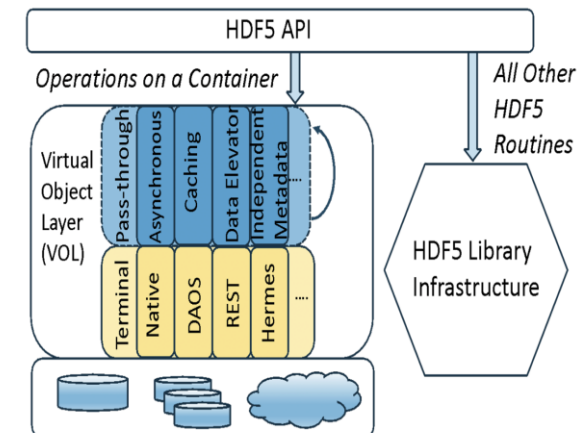


File formats

- CSV : Sequential text file, not really adapted to //
- JSON : Handle complex data, nice to describe metadata
- HDF5 : Parallel format with many features
- Ensight Gold : 3D Visualization format (binary and writing in // using mpi-IO)
- XDMF+HDF5 : 3D Visualization format

Scaling up

- IO is currently a bottleneck to scale up (many cores/nodes)
- One file per proc : generally not recommended
- Current solutions identified : HDF5, SIONlib, ADIOS
- Strategy envisaged
 - Asynchronous I/O [1] : background thread using task managers, hiding I/O latency
 - Caching with node-local memory and storage [2]
- HDF5 and Virtual Object Layer (VOL)
 - Same API, but allows different underlying storage mechanisms



Weak scaling

[1]: <https://github.com/hpc-io/vol-async>
 [2]: <https://github.com/hpc-io/vol-cache>

Multiphysics coupling : PDEs

- Coupling interface through mesh discretization
- Strong/weak coupling : one-way or two-way
- Our application : coupling Urban Building and Urban Air Pollution pilots

Requirements

- Data exchange between two (or more) simulation frameworks in HPC context.
- Communication peer-to-peer (objective is to reduce the use of file system)
- Unbalanced computational resource

Potential solution for coupling solution between UAP and UB

- [MUSCLE3](#)

Conclusion



Current/Next Steps

- Currently benchmarking on EuroHPC systems (LUMI, Vega, Discoverer,...) + PSNC systems (Poland)
- Develop multi-fidelity models for buildings
- Automate workflow
- Vegetation, urban furniture
- Coupling with UAP

Identified Challenges/Bottlenecks

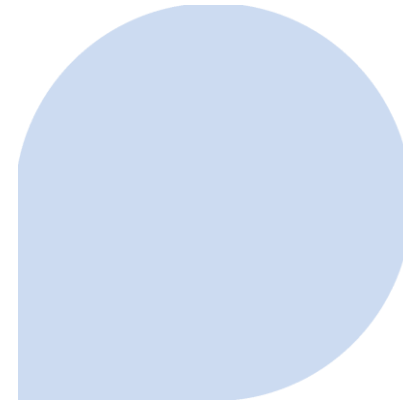
- Large-scale mesh generation : surface mesh and volume mesh (adapted for CFD)
- Parallel mesh adaptation
- Multi fidelity representation (geometry and physics)
- Mesh and physic-based/LOD partitioning and load balancing
- I/O
- Multiphysics coupling



**Thank you for your
attention**

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